# Regularization of an inverse nonlinear parabolic problem with time-dependent coefficient and locally Lipschitz source term

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#### Abstract

We consider a backward problem of finding a function u satisfying a nonlinear parabolic equation in the form  $u_t + a(t)Au(t) = f(t, u(t))$  subject to the final condition  $u(T) = \varphi$ . Here A is a positive self-adjoint unbounded operator in a Hilbert space H and f satisfies a locally Lipschitz condition. This problem is ill-posed. Using quasi-reversibility method, we shall construct a regularized solution  $u_{\varepsilon}$  from the measured data  $a_{\varepsilon}$  and  $\varphi_{\varepsilon}$ . We show that the regularized problem are well-posed and that their solutions converge to the exact solutions. Error estimate is given.

**Keywords and phrases:** Nonlinear parabolic problem, Backward problem, Quasi-reversibility, Ill-posed problem, Contraction principle.

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### 1. Introduction

Let  $(H, \|\cdot\|)$  be a Hilbert space with the inner product  $(\cdot, \cdot)$ . Let *A* be a positive self-adjoint operator defined on a dense subspace  $D(A) \subset H$  such that -A generates a compact contraction semi-group S(t) on *H*. Let  $f : [0, T] \times H \to H$  satisfy the locally Lipschitz condition: for each M > 0, there exists k(M) > 0 such that

$$\|f(t,u) - f(t,v)\| \le k(M) \|u - v\| \text{ if } \max\{\|u\|, \|v\|\} \le M.$$
(1)

We shall consider a backward problem of finding a function  $u : [0, T] \rightarrow H$  such that

$$u_t + a(t)Au(t) = f(t, u(t)), \quad 0 < t < T,$$
  
$$u(T) = \varphi,$$
 (2)

where  $a \in C([0, T])$  is a given real-valued function and  $\varphi \in H$  is a prescribed final value.

This nonlinear nonhomogeneous problem is severely ill-posed. In fact, the problem is extremely sensitive to measurement errors (see, e.g., [2]). The final data is usually the result of discrete experimental measurements and is subject to error. Hence, a solution corresponding to the data does not

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always exist, and in the case of existence, does not depend continuously on the given data. This, of course, shows that a naturally numerical treatment is impossible. Thus one has to resort to a regularization.

The backward problem (2) has a long history. The linear homogeneous case f = 0 has been considered by many authors such as quasi-reversibility method [7, 8, 6, 10, 1], quasi-boundary value method [4, 5]. The problem with constant coefficient and nonlinear source term, i.e.

$$u_t + Au(t) = f(t, u(t)), \quad 0 < t < T,$$
  

$$u(T) = \varphi,$$
(3)

was studied in [3, 12, 13, 14]. However, in these papers, the source function f is assumed to be globally Lipschitz, that is

$$||f(t, u) - f(t, v)|| \le k||u - v||$$

where k is independent of t, u. Recently, in [15], a regularization method for locally Lipschitz source term has been established under an extra condition on the source term:

There exists a constant  $L \ge 0$ , such that  $\langle f(t, u) - f(t, v), u - v \rangle + ||u - v||^2 \ge 0$ .

This condition holds for the source  $f(u) = u ||u||_{H}^{2}$  (see [15]). However, it is not satisfied in several cases, for example,  $f(u) = au - bu^{3}$  (b > 0) of the Ginzburg-Landau equation. Hence, another regularization method which can be applied to any locally Lipschitz source term is of interests. In this paper, we shall assume that the source term f is locally Lipschitz with respect to u (i.e. f satisfies (1)). Our main idea is approximating the function f by a sequence  $f_{\varepsilon}$  of Lipschitz functions

$$||f_{\varepsilon}(t, u) - f_{\varepsilon}(t, v)|| \le k_{\varepsilon} ||u - v||.$$

Then, we use the results in [12, 14] to approximate problem (3) by the following problem

$$\frac{d}{dt}u^{\varepsilon}(t) + A_{\varepsilon}u^{\varepsilon}(t) = B(\varepsilon, t)f_{\varepsilon}(t, u^{\varepsilon}(t)), \quad t \in [0, T],$$

$$u^{\varepsilon}(T) = \varphi$$
(4)

where  $A_{\varepsilon}$ ,  $B(\varepsilon, t)$  are defined appropriately.

When the perturbed coefficient *a* is time-dependent, the problems turns to be more complicated. Indeed, the strategies used for constant coefficient cannot be applied to the time-dependent coefficient case. The problem with time-dependent coefficient has been recently investigated in [9]. However, the methods proposed in [9] can be merely applied either for zero source with perturbed time-dependent coefficient or for globally Lipschitz source with unperturbed time-dependent coefficient. We would like to emphasize that our regularization method for constant coefficient also works for unperturbed time-dependent coefficient.

The paper is organized as follows. In Section 2, we shall investigate a regularization method for the case of constant coefficient  $a \equiv 1$ . In particular, we shall give precise formulas of  $A_{\varepsilon}$ ,  $B(\varepsilon, t)$  and  $f_{\varepsilon}(t, v)$ ; show that the regularized problem (4) is well-posed and prove the convergence of  $u^{\varepsilon}$  to the exact solution in C([0, T]; H) with explicit error estimates. Section 3 provides a regularization method for perturbed time-dependent coefficient a(t).

#### 2. Regularization of backward parabolic problem with constant coefficient

#### 2.1. The well-posedness of the regularized problem (4)

We shall first give the precise formula of the operator S(t). Assume that A is a positive self-adjoint operator in the separable Hilbert space  $(H, (\cdot, \cdot))$  and 0 is in its resolvent set. Since  $A^{-1}$  is a compact self-adjoint operator, there is an orthonormal eigenbasis  $\{\phi_n\}_{n=1}^{\infty}$  of H corresponding to a sequence of its eigenvalues  $\{\lambda_n^{-1}\}_{n=1}^{\infty}$  in which

$$0 < \lambda_1 \le \lambda_2 \le \lambda_3 \le \dots \lim_{n \to \infty} \lambda_n = \infty.$$

Thus  $A^{-1}\phi_n = \lambda_n^{-1}\phi_n$  and  $A\phi_n = \lambda_n\phi_n$  for each  $n \ge 1$ . The compact contraction semi-group S(t) corresponding to A is

$$S(t)v = \sum_{n=1}^{\infty} e^{-t\lambda_n}(\phi_n, v)\phi_n, \ v \in H.$$

Problem (3) can be written in the language of semi-group as follows.

$$u(t) = S(t-T)\varphi - \int_{t}^{T} S(t-s)f(s,u(s)) \,\mathrm{d}s.$$
(5)

For each  $\varepsilon > 0$ , we define the bounded operator

$$A_{\varepsilon}(v) = -\frac{1}{T} \sum_{n=1}^{\infty} \ln(\varepsilon + e^{-T\lambda_n})(\phi_n, v)\phi_n.$$
(6)

The compact contraction semi-group  $S_{\varepsilon}(t)$  corresponding to  $A_{\varepsilon}$  is

$$S_{\varepsilon}(t)v = \sum_{n=1}^{\infty} \left(\varepsilon + e^{-T\lambda_n}\right)^{\frac{t}{T}} (\phi_n, v)\phi_n, \ v \in H.$$

Obviously, (4) can be written as

$$u^{\varepsilon}(t) = S_{\varepsilon}(t-T)\varphi - \int_{t}^{T} S_{\varepsilon}(t-s)B(\varepsilon,s)f_{\varepsilon}(s,u^{\varepsilon}(s))\,\mathrm{d}s,\tag{7}$$

For each  $t \leq T$ , define by  $B(\varepsilon, t)$  the bounded operator

$$B(\varepsilon, t) := S_{\varepsilon}(t - T)S(T - t).$$

The operator  $B(\varepsilon, t)$  can be written explicitly as

$$B(\varepsilon,t)(v) = \sum_{n=1}^{\infty} (1 + \varepsilon e^{T\lambda_n})^{\frac{t}{T}-1}(\phi_n, v)\phi_n, \ v \in H.$$
(8)

In particular,

$$B(\varepsilon, t)\phi_n = S_{\varepsilon}(t-T)S(T-t)\phi_n = S_{\varepsilon}(t-T)\left(e^{-(T-t)\lambda_n}\phi_n\right)$$
$$= \left(\varepsilon + e^{-T\lambda_n}\right)^{\frac{t-T}{T}}e^{-(T-t)\lambda_n}\phi_n = (\varepsilon e^{T\lambda_n} + 1)^{\frac{t-T}{T}}\phi_n, \ \forall n \ge 1.$$

Our later calculations will be represented via operators  $S_{\varepsilon}(t)$  and  $B(\varepsilon, t)$ . We shall need some upper bounds of these operators.

**Lemma 1.** Let  $0 \le t \le T$ . Then  $S_{\varepsilon}(-t)$  and  $B(\varepsilon, t)$  are bounded operators and

 $||S_{\varepsilon}(-t)|| \leq \varepsilon^{-\frac{t}{T}}, \qquad ||B(\varepsilon, t)|| \leq 1.$ 

Moreover,

$$\|[B(\varepsilon,t)-I]\phi_n\| \leq \varepsilon e^{T\lambda_n}, \forall n \geq 1.$$

*Proof.* For each  $n \ge 1$ , one has

$$\begin{split} \|S_{\varepsilon}(t)\phi_{n}\| &= \left(\varepsilon + e^{-T\lambda_{n}}\right)^{-\frac{t}{T}} \leq \varepsilon^{-\frac{t}{T}},\\ \|B(\varepsilon,t)\phi_{n}\| &= \left(1 + \varepsilon e^{T\lambda_{n}}\right)^{\frac{t}{T}-1} \leq 1\\ \|[I - B(\varepsilon,t)]\phi_{n}\| &= 1 - \left(1 + \varepsilon e^{T\lambda_{n}}\right)^{\frac{t}{T}-1}\\ &\leq 1 - \left(1 + \varepsilon e^{T\lambda_{n}}\right)^{-1} \leq \varepsilon e^{T\lambda_{n}}. \end{split}$$

The desired result follows.

Next, we define an approximation  $f_{\varepsilon}$  of f. Recall that  $f : [0, T] \times H \to H$  satisfies the locally Lipschitz condition (1):

For each M > 0, there exists k(M) > 0 such that  $||f(t, u) - f(t, v)|| \le k(M) ||u - v||$  if  $\max \{||u||, ||v||\} \le M$ .

It is obvious that the function k is increasing on  $[0, \infty)$ . We can choose a set  $\{M_{\varepsilon} > 0\}_{\varepsilon>0}$  satisfying  $\lim_{\varepsilon \to 0^+} M_{\varepsilon} = \infty$  and  $k(M_{\varepsilon}) \le \ln(\ln(\varepsilon^{-1}))/(4T)$ . Define

$$f_{\varepsilon}(t,v) = f\left(t, \min\left\{\frac{M_{\varepsilon}}{\|v\|}, 1\right\}v\right), \quad \forall (t,v) \in [0,T] \times H,$$
(9)

in particular  $f_{\varepsilon}(t,0) = f(t,0)$ . With this definition, we claim that  $f_{\varepsilon}$  is a Lipschitz function. In fact, we have

**Lemma 2.** For  $\varepsilon > 0$ ,  $t \in [0, T]$  and  $v_1, v_2 \in H$ , one has

$$\|f_{\varepsilon}(t, v_1) - f_{\varepsilon}(t, v_2)\| \le k_{\varepsilon} \|v_1 - v_2\|,$$

where  $k_{\varepsilon} = 2k(M_{\varepsilon}) \leq \ln(\ln(\varepsilon^{-1}))/(2T)$ .

*Proof.* Due to the continuity, it is enough to prove Lemma 2 for non-zero vectors  $v_1$ ,  $v_2$ . We can assume that  $||v_1|| \ge ||v_2|| > 0$ . Using the locally Lipschitz property of f, one has

$$\begin{aligned} \|f_{\varepsilon}(t,v_{1}) - f_{\varepsilon}(t,v_{2})\| &= \left\| f\left(t,\min\left\{\frac{M_{\varepsilon}}{\|v_{1}\|},1\right\}v_{1}\right) - f\left(t,\min\left\{\frac{M_{\varepsilon}}{\|v_{2}\|},1\right\}v_{2}\right) \right\| \\ &\leq k(M_{\varepsilon}) \left\|\min\left\{\frac{M_{\varepsilon}}{\|v_{1}\|},1\right\}v_{1} - \min\left\{\frac{M_{\varepsilon}}{\|v_{2}\|},1\right\}v_{2}\right\|. \end{aligned}$$

It remains to show that

$$\left\|\min\left\{\frac{M_{\varepsilon}}{\|v_1\|},1\right\}v_1-\min\left\{\frac{M_{\varepsilon}}{\|v_2\|},1\right\}v_2\right\|\leq 2\left\|v_1-v_2\right\|.$$

This inequality is trivial if  $M_{\varepsilon} \ge ||v_1|| \ge ||v_2||$ . When  $||v_1|| \ge ||v_2|| \ge M_{\varepsilon}$ , one has

$$\begin{split} \left\| \frac{M_{\varepsilon}}{\|v_1\|} v_1 - \frac{M_{\varepsilon}}{\|v_2\|} v_2 \right\| &= M_{\varepsilon} \left\| \frac{v_1 - v_2}{\|v_1\|} + \frac{\|v_2\| - \|v_1\|}{\|v_1\| \cdot \|v_2\|} v_2 \right\| \\ &\leq M_{\varepsilon} \left( \left\| \frac{v_1 - v_2}{\|v_1\|} \right\| + \left\| \frac{\|v_2\| - \|v_1\|}{\|v_1\| \cdot \|v_2\|} v_2 \right\| \right) \\ &= \frac{M_{\varepsilon}}{\|v_1\|} \left( \|v_1 - v_2\| + \|v_2\| - \|v_1\| \right) \leq 2 \|v_1 - v_2\| \,. \end{split}$$

Finally, if  $||v_1|| \ge M_{\varepsilon} \ge ||v_2||$  then

$$\begin{aligned} \left\| \frac{M_{\varepsilon}}{\|v_1\|} v_1 - v_2 \right\| &= \left\| \frac{M_{\varepsilon} - \|v_1\|}{\|v_1\|} v_1 + v_1 - v_2 \right\| \\ &\leq \left\| \frac{M_{\varepsilon} - \|v_1\|}{\|v_1\|} v_1 \right\| + \|v_1 - v_2\| \\ &= \left\| M_{\varepsilon} - \|v_1\| + \|v_1 - v_2\| \le 2 \|v_1 - v_2\|. \end{aligned}$$

Here we have used the inequality  $|M_{\varepsilon} - ||v_1||| \le ||v_2|| - ||v_1||| \le ||v_1 - v_2||$ .

We now study the existence, the uniqueness and the stability of a (weak) solution of problem (4).

**Theorem 1.** Let  $\varepsilon > 0$ . For each  $\varphi \in H$ , problem (4) has a unique solution  $u^{\varepsilon} \in C([0, T]; H)$ . Moreover, the solutions depend continuously on the data in the sense that if  $u_j^{\varepsilon}$  is the solution corresponding to  $\varphi_j$ , j = 1, 2, then

$$\|u_1^{\varepsilon}(t) - u_2^{\varepsilon}(t)\| \le \varepsilon^{\frac{t-T}{T}} e^{k_{\varepsilon}(T-t)} \|\varphi_1 - \varphi_2\|_{\varepsilon}$$

#### Proof. Step 1: Uniqueness

Fix  $\varphi \in H$ . For each  $w \in C([0, T]; H)$ , define by

$$F(w)(t) := S_{\varepsilon}(t-T)\varphi - \int_{t}^{T} S_{\varepsilon}(t-s)B(\varepsilon,s)f_{\varepsilon}(s,w(s)) \,\mathrm{d}s.$$

It is sufficient to show that F has a unique fixed point in C([0, T]; H). This fact will be proved by contraction principle.

We claim by induction with respect to m = 1, 2, ... that, for all  $w, v \in C([0, T]; H)$ ,

$$\|F^{m}(w)(t) - F^{m}(v)(t)\| \le \left(\frac{k_{\varepsilon}}{\varepsilon}\right)^{m} \frac{(T-t)^{m}}{m!} \||w(s) - v(s)|\|,$$

$$(10)$$

where  $\|\|.\|\|$  is the sup norm in C([0, T]; H). For m = 1, using lemmas 1 and 2, we have

$$||F(w)(t) - F(v)(t)|| = \left\| \int_{t}^{T} S_{\varepsilon}(t-s)B(\varepsilon,s) \left[ f_{\varepsilon}(s,w(s)) - f_{\varepsilon}(s,v(s)) \right] ds \right\|$$
  

$$\leq \int_{t}^{T} ||S_{\varepsilon}(t-s)|| \cdot ||B(\varepsilon,s)|| \cdot ||f_{\varepsilon}(s,w(s)) - f_{\varepsilon}(s,v(s))|| ds$$
  

$$\leq k_{\varepsilon} \int_{t}^{T} \varepsilon^{\frac{t-s}{T}} ||w-v|| ds \leq \frac{k_{\varepsilon}}{\varepsilon} \int_{t}^{T} ||w-v|| ds$$
  

$$\leq \frac{k_{\varepsilon}}{\varepsilon} (T-t)|||w(s) - v(s)|||.$$

Suppose that (10) holds for m = j. We prove that (10) holds for m = j + 1. Infact, we have

$$\begin{split} \left\| F^{j+1}(w)(t) - F^{j+1}(v)(t) \right\| &= \left\| F(F^{j}(w))(t) - F(F^{j}(v))(t) \right\| \\ &\leq \frac{k_{\varepsilon}}{\varepsilon} \int_{t}^{T} \left\| F^{j}(w)(s) - F^{j}(v)(s) \right\| ds \\ &\leq \frac{k_{\varepsilon}}{\varepsilon} \int_{t}^{T} \left( \frac{k_{\varepsilon}}{\varepsilon} \right)^{j} \frac{(T-s)^{j}}{j!} \| |w(s) - v(s)| \| ds \\ &= \left( \frac{k_{\varepsilon}}{\varepsilon} \right)^{j+1} \frac{(T-t)^{j+1}}{(j+1)!} \| |w(s) - v(s)| \|. \end{split}$$

Therefore (11) holds for all m = 1, 2, ... by the induction principle. In particular, one has

$$|||F^{m}(w)(t) - F^{m}(v)(t)||| \le \left(\frac{k_{\varepsilon}T}{\varepsilon}\right)^{m} \frac{1}{m!} |||w(s) - v(s)|||.$$

Since

$$\lim_{m\to\infty}\left(\frac{k_{\varepsilon}T}{\varepsilon}\right)^m\frac{1}{m!}=0,$$

there exists a positive integer number  $m_0$  such that  $F^{m_0}$  is a contraction mapping. It follows that  $F^{m_0}$  has a unique fixed point  $u^{\varepsilon}$  in C([0, T]; H). Since  $F^{m_0}(F(u^{\varepsilon})) = F(F^{m_0}(u^{\varepsilon})) = F(u^{\varepsilon})$ , we obtain  $F(u^{\varepsilon}) = u^{\varepsilon}$  due to the uniqueness of the fixed point of  $F^{m_0}$ . The uniqueness of the fixed point of F also follows the uniqueness fixed point of  $F^{m_0}$ . The unique fixed point  $u^{\varepsilon}$  of F is the solution of (7) corresponding to final value  $\varphi$ .

## Step 2: Continuous dependence on the data

We now let  $u_1^{\varepsilon}$  and  $u_2^{\varepsilon}$  be two solutions corresponding to final values  $\varphi_1$  and  $\varphi_2$ , respectively. In the same manner as Step 1, we have for every  $w, v \in C([0, T]; H)$ 

$$\|F(w)(t) - F(v)(t)\| \le k_{\varepsilon} \int_{t}^{T} \varepsilon^{\frac{t-s}{T}} \|w(s) - v(s)\| \,\mathrm{d}s.$$

Hence

$$\begin{split} \left\| u_{1}^{\varepsilon}(t) - u_{2}^{\varepsilon}(t) \right\| &= \left\| S_{\varepsilon}(t-T) \left(\varphi_{1} - \varphi_{2}\right) + F(u_{1}^{\varepsilon})(t) - F(u_{2}^{\varepsilon})(t) \right\| \\ &\leq \left\| S_{\varepsilon}(t-T) \right\| \cdot \left\| \varphi_{1} - \varphi_{2} \right\| + \left\| F(u_{1}^{\varepsilon})(t) - F(u_{2}^{\varepsilon})(t) \right\| \\ &\leq \varepsilon^{\frac{t-T}{T}} \left\| \varphi_{1} - \varphi_{2} \right\| + k_{\varepsilon} \int_{t}^{T} e^{\frac{t-s}{T}} \left\| u_{1}^{\varepsilon}(s) - u_{2}^{\varepsilon}(s) \right\| ds. \end{split}$$

The latter inequality can be written as

$$\varepsilon^{-\frac{t}{T}} \left\| u_1^{\varepsilon}(t) - u_2^{\varepsilon}(t) \right\| \le \varepsilon^{-1} \left\| \varphi_1 - \varphi_2 \right\| + k_{\varepsilon} \int_t^T e^{-\frac{s}{T}} \left\| u_1^{\varepsilon}(s) - u_2^{\varepsilon}(s) \right\| ds.$$

It follows from Gronwall's inequality that

$$\varepsilon^{-\frac{t}{T}} \left\| u_1^{\varepsilon}(t) - u_2^{\varepsilon}(t) \right\| \le \varepsilon^{-1} e^{k_{\varepsilon}(T-t)} \left\| \varphi_1 - \varphi_2 \right\|, \ t \in [0,T].$$

This completes the proof of Theorem 1.

#### 2.2. Regularization of problem (3)

Our purpose in this section is to construct a regularized solution of the ill-posed problem (3). We mention that the existence of a solution of (3) is not considered here. Instead, we assume that there is an exact solution *u* corresponding to the exact datum  $\varphi$ , and our aim is to construct, from the given datum  $\varphi_{\varepsilon}$  approximating  $\varphi$ , a regularized solution  $U_{\varepsilon}$  which approximates *u*.

Denote by  $u^{\varepsilon}$  the solution of problem (4) corresponding to the final condition  $\varphi_{\varepsilon}$ . We shall show that for each fixed time t > 0, the function  $u^{\varepsilon}(t)$  gives a good approximation of u(t), where the order of approximation is  $\varepsilon^{\frac{t}{2T}}$ . However, it is difficult to derive an approximation at t = 0. We therefore need an adjustment in choosing the regularized solution. The main idea is that we first use the continuity of u to approximate the initial value u(0) by  $u(t_{\varepsilon})$  for some suitable small time  $t_{\varepsilon} > 0$ , and then approximate  $u(t_{\varepsilon})$  by  $u^{\varepsilon}(t_{\varepsilon})$ . The parameter  $t_{\varepsilon}$  will be choosen as follows.

**Lemma 3.** Let T > 0 and let  $\varepsilon > 0$  small enough. There exists a unique  $t_{\varepsilon} > 0$  such that  $\varepsilon^{\frac{t_{\varepsilon}}{2T}} = t_{\varepsilon}$ . *Moreover,* 

$$t_{\varepsilon} \le \frac{2T \ln(\ln(\varepsilon^{-1}))}{\ln(\varepsilon^{-1})}$$

*Proof.* Note that each solution t > 0 of  $\varepsilon^{\frac{t}{2T}} = t$  is a zero of the function

$$h(t) = \ln(t) + \frac{\ln(\varepsilon^{-1})}{2T}t, \qquad t > 0.$$

We have *h* is strictly increasing as h'(t) > 0. Moreover,  $\lim_{t \to t} h(t) = -\infty$  and

$$h\left(\frac{2T\ln(\ln(\varepsilon^{-1}))}{\ln(\varepsilon^{-1})}\right) = \ln\left[2T\ln(\ln(\varepsilon^{-1}))\right] > 0$$

for  $\varepsilon > 0$  small enough. Thus the equation h(t) = 0 has a unique solution  $t_{\varepsilon} > 0$  such that

$$t_{\varepsilon} \le \frac{2T \ln\left(\ln\left(\frac{1}{\varepsilon}\right)\right)}{\ln\left(\frac{1}{\varepsilon}\right)}$$

We have the following regularization result.

**Theorem 2.** Let  $u \in C^1([0, T]; H)$  be a solution of problem (3) corresponding to  $\varphi \in H$ . Assume that

$$\sup_{t\in[0,T]} \left[ \sum_{n=1}^{\infty} e^{2T\lambda_n} |(\phi_n, u(t))|^2 + ||u'(t)|| \right] = M < \infty.$$

Let  $\varphi_{\varepsilon}$  be a measured datum satisfying  $\|\varphi_{\varepsilon} - \varphi\| \le \varepsilon$  with  $\varepsilon > 0$ , and let  $u^{\varepsilon}$  be the solution of problem (4) corresponding to  $\varphi_{\varepsilon}$ . Choose  $t_{\varepsilon} > 0$  as in Lemma 3. Define the regularized solution  $U^{\varepsilon} : [0, T] \to H$  by

$$U^{\varepsilon}(t) = u^{\varepsilon}(\max\{t, t_{\varepsilon}\}), \ t \in [0, T]$$

Then one has the error estimate, for  $\varepsilon > 0$  small enough,  $t \in [0, T]$ ,

$$\|U^{\varepsilon}(t) - u(t)\| \le (2M+1)\min\left\{\varepsilon^{\frac{t}{2T}}, \frac{2T\ln(\ln(\varepsilon^{-1}))}{\ln(\varepsilon^{-1})}\right\}$$

*Proof.* We have in view of (5)

$$u(t) = S(t-T)\varphi - \int_{t}^{T} S(t-s)f(s, u(s)) \,\mathrm{d}s.$$

Using  $B(\varepsilon, t) = S_{\varepsilon}(t - T)S(T - t)$ , one has

$$B(\varepsilon,t)u(t) = S_{\varepsilon}(t-T)\varphi - \int_{t}^{T} S_{\varepsilon}(t-s)B(\varepsilon,s)f(s,u(s))\,\mathrm{d}s.$$

We have in view of (7)

$$u^{\varepsilon}(t) = S_{\varepsilon}(t-T)\varphi_{\varepsilon} - \int_{t}^{T} S_{\varepsilon}(t-s)B(\varepsilon,s)f_{\varepsilon}(s,u^{\varepsilon}(s))\,\mathrm{d}s.$$

Thus

$$u^{\varepsilon}(t) - u(t) = S_{\varepsilon}(t - T) (\varphi_{\varepsilon} - \varphi) + [B(\varepsilon, t) - I] u(t) + \int_{t}^{T} S_{\varepsilon}(t - s)B(\varepsilon, s) [f_{\varepsilon}(s, u^{\varepsilon}(s)) - f(s, u(s))] ds.$$

Using Lemma 1 and noting that  $f(s, u(s)) = f_{\varepsilon}(s, u(s))$  for  $\varepsilon > 0$  small enough,  $M_{\varepsilon} \ge \sup_{t \in [0,T]} ||u(t)||$ , we get

$$\begin{split} \|u^{\varepsilon}(t) - u(t)\| &\leq \|S_{\varepsilon}(t - T)\| \cdot \|\varphi_{\varepsilon} - \varphi\| + \|[B(\varepsilon, t) - I] u(t)\| + \\ &+ \int_{t}^{T} \|S_{\varepsilon}(t - s)\| \cdot \|B(\varepsilon, s)\| \cdot \|f_{\varepsilon}(s, u^{\varepsilon}(s)) - f(s, u(s))\| \, \mathrm{d}s \\ &\leq \varepsilon^{\frac{t - T}{T}} \cdot \varepsilon + \varepsilon \sqrt{\sum_{n=1}^{\infty} e^{2T\lambda_{n}} |(\phi_{n}, u)|^{2}} + k_{\varepsilon} \int_{t}^{T} \varepsilon^{\frac{t - s}{T}} \|u^{\varepsilon}(s) - u(s)\| \, \mathrm{d}s \\ &\leq (M + 1)\varepsilon^{\frac{t}{T}} + k_{\varepsilon} \int_{t}^{T} \varepsilon^{\frac{t - s}{T}} \|u^{\varepsilon}(s) - u(s)\| \, \mathrm{d}s. \end{split}$$

The latter inequality can be written as

$$\varepsilon^{-\frac{t}{T}} \| u^{\varepsilon}(t) - u(t) \| \le (M+1) + k_{\varepsilon} \int_{t}^{T} \varepsilon^{-\frac{s}{T}} \| u^{\varepsilon}(s) - u(s) \| \mathrm{d}s.$$

It follows from Gronwall's inequality that

$$\varepsilon^{-\frac{t}{T}} \| u^{\varepsilon}(t) - u(t) \| \le (M+1)e^{k_{\varepsilon}T}, \ \forall t \in (0,T].$$

In particular, if  $t \in [t_{\varepsilon}, T]$  then

$$\begin{split} \|U^{\varepsilon}(t) - u(t)\| &= \|u^{\varepsilon}(t) - u(t)\| \leq (M+1)e^{k_{\varepsilon}T}\varepsilon^{\frac{1}{T}} \\ &\leq (M+1)\varepsilon^{\frac{1}{2T}} \leq \frac{2T(M+1)\ln(\ln(\varepsilon^{-1}))}{\ln(\varepsilon^{-1})}, \end{split}$$

where we have used

$$e^{k_{\varepsilon}T} \leq \sqrt{\ln(\varepsilon^{-1})} \leq \frac{\ln(\varepsilon^{-1})}{2T\ln(\ln(\varepsilon^{-1}))} \leq t_{\varepsilon}^{-1} = \varepsilon^{-\frac{t_{\varepsilon}}{2T}} \leq \varepsilon^{-\frac{t}{2T}}.$$
(11)

Let us now consider  $t \in [0, t_{\varepsilon}]$ . One has

$$||U^{\varepsilon}(t) - u(t)|| = ||u^{\varepsilon}(t_{\varepsilon}) - u(t)|| \le ||u^{\varepsilon}(t_{\varepsilon}) - u(t_{\varepsilon})|| + ||u(t_{\varepsilon}) - u(t)||.$$

Due to the continuity of  $u_t$ , we get for  $\varepsilon$  small enough

$$\|u(t_{\varepsilon})-u(t)\| = \left\|\int_{t}^{t_{\varepsilon}} u_t(s)ds\right\| \leq \int_{0}^{t_{\varepsilon}} \|u_t(s)\|\,ds \leq Mt_{\varepsilon}.$$

Thus, for  $t \in [0, t_{\varepsilon}]$ ,

$$\begin{aligned} \|U^{\varepsilon}(t) - u(t)\| &\leq (M+1)\varepsilon^{\frac{t_{\varepsilon}}{2T}} + Mt_{\varepsilon} = (2M+1)t_{\varepsilon} \\ &\leq (2M+1)\min\left\{\varepsilon^{\frac{t}{2T}}, \frac{2T\ln(\ln(\varepsilon^{-1}))}{\ln(\varepsilon^{-1})}\right\} \end{aligned}$$

This completes the proof of Theorem 2.

#### 3. Regularization of backward parabolic problem with time-dependent coefficient

In this section, we consider the following backward nonlinear parabolic problem with timedependent coefficient

$$u_t + a(t)Au(t) = f(t, u(t)), \quad 0 < t < T,$$
  
$$u(T) = \varphi, \tag{12}$$

where  $a \in C([0, T])$  is given. The function a is noised by the perturbed data  $a_{\varepsilon} \in C[0, T]$  such that

$$\|a_{\varepsilon} - a\|_{C([0,T])} \le \varepsilon.$$
(13)

where the norm  $\|\cdot\|_{C([0,T])}$  is given by the sup norm, i.e.,  $\|v\|_{C([0,T])} = \sup_{0 \le t \le T} |v(t)|$  for every continuous function  $v : [0, T] \to \mathbb{R}$ . We would like to emphasize that it is impossible to apply the technique in Section 2 to solve problem (12) when the time-dependent coefficient is perturbed by noise. Therefore, we investigate a new regularized problem as follows

$$\begin{cases} \frac{d}{dt} v_{\varepsilon}(t) + a_{\varepsilon}(t) \widetilde{A}_{\varepsilon} v_{\varepsilon}(t) = f_{\varepsilon}(t, v_{\varepsilon}(t)), \quad 0 < t < 1, \\ v_{\varepsilon}(T) = \varphi_{\varepsilon}, \end{cases}$$
(14)

where  $\widetilde{A}_{\varepsilon}$  is defined by

$$\widetilde{A}_{\varepsilon}(v) := -\frac{1}{QT} \sum_{n=1}^{\infty} \ln\left(\varepsilon + e^{-QT\lambda_n}\right) \langle v, \phi_n \rangle \phi_n \tag{15}$$

and  $Q = ||a_{\varepsilon}||_{C([0,T])}$ .

The regularization result for time-dependent perturbed coefficient is given in the following theorem.

**Theorem 3.** Let  $u \in C^1([0, T]; H)$  be a solution of problem (12) corresponding to  $\varphi \in H$ . Assume that

$$\sup_{e[0,T]} \left[ \sum_{n=1}^{\infty} e^{2QT\lambda_n} |(\phi_n, u(t))|^2 + ||u'(t)|| \right] = E_Q < \infty.$$

Let  $\varphi_{\varepsilon}$  and  $a_{\varepsilon}$  be measured data satisfying  $\|\varphi_{\varepsilon} - \varphi\| \le \varepsilon$  and  $\|a_{\varepsilon} - a\|_{C([0,T])} \le \varepsilon$  for  $\varepsilon > 0$ . We denote by  $v_{\varepsilon}$  the solution of problem (14) corresponding to  $\varphi_{\varepsilon}$  and  $a_{\varepsilon}$ . Choose  $t_{\varepsilon} > 0$  as in Lemma 3. Define the regularized solution  $W^{\varepsilon} : [0, T] \to H$  by

$$W^{\varepsilon}(t) = v_{\varepsilon}(\max\{t, t_{\varepsilon}\}), \ t \in [0, T].$$

Then one has the following error estimate for  $\varepsilon > 0$  small enough and  $t \in [0, T]$ ,

$$\|W^{\varepsilon}(t) - u(t)\| \le 2E_Q \sqrt{2\left(\frac{1}{Q} + 1\right)}e^{2T} \min\left\{\varepsilon^{\frac{t}{2T}}, \frac{2T\ln(\ln(\varepsilon^{-1}))}{\ln(\varepsilon^{-1})}\right\}.$$

*Proof.* The existence of solutions to problem (12) can be proved in the same manner as Theorem 1. It remains to prove the error estimation between  $W_{\varepsilon}$  and u. To this end, we first need the error estimation between  $u_{\varepsilon}$  and u. The technique we use here is different from Theorem 2. The problem (12) can be written as

$$\begin{cases} u'(t) + a_{\varepsilon}(t)\widetilde{A}_{\varepsilon}u(t) = a_{\varepsilon}(t)\widetilde{A}_{\varepsilon}u(t) - a(t)Au(t) + f(t,u(t)), \\ u(T) = \varphi. \end{cases}$$
(16)

Recall that  $v_{\varepsilon}$  solves the following equation

t

$$\begin{cases} v'_{\varepsilon}(t) + a_{\varepsilon}(t)\widetilde{A}_{\varepsilon}v_{\varepsilon}(t) &= f_{\varepsilon}(t, v_{\varepsilon}(t)), \\ v_{\varepsilon}(T) &= \varphi_{\varepsilon}. \end{cases}$$
(17)

Substituting (17) into (16) bothsides, we obtain

$$\begin{cases} v_{\varepsilon}'(t) - u'(t) = -a_{\varepsilon}(t)\widetilde{A}_{\varepsilon}(v_{\varepsilon}(t) - u(t)) - a_{\varepsilon}(t)\widetilde{A}_{\varepsilon}u(t) + a(t)Au(t) \\ + f_{\varepsilon}(t, v_{\varepsilon}(t)) - f(t, u(t)), \end{cases}$$
(18)  
$$v_{\varepsilon}(T) - u_{\varepsilon}(T) = \varphi_{\varepsilon} - \varphi.$$

For  $\tilde{b} > 0$ , we define by

$$z_{\varepsilon}(t) := e^{\widetilde{b}(t-T)} \Big( v_{\varepsilon}(t) - u(t) \Big).$$

By differentiating  $z_{\varepsilon}(t)$  with respect t and combining to (18) gives

$$z_{\varepsilon}'(t) = \widetilde{b}e^{\widetilde{b}(t-T)}(v_{\varepsilon}(t) - u(t)) + e^{\widetilde{b}(t-T)}(v_{\varepsilon}'(t) - u'(t))$$

$$= \widetilde{b}z_{\varepsilon}(t) + e^{\widetilde{b}(t-T)}\left[-a_{\varepsilon}(t)\widetilde{A}_{\varepsilon}(v_{\varepsilon}(t) - u(t)) + f(t, v_{\varepsilon}(t)) - f(t, u(t))\right]$$

$$-e^{\widetilde{b}(t-T)}\left[(a_{\varepsilon}(t) - a(t))Au(t) + a_{\varepsilon}(t)(\widetilde{A}_{\varepsilon} - A)u(t)\right]$$

$$= \widetilde{b}z_{\varepsilon}(t) - \widetilde{A}_{\varepsilon}z_{\varepsilon}(t) + e^{\widetilde{b}(t-T)}\left[f(t, v_{\varepsilon}(t)) - f(t, u(t))\right]$$

$$-e^{\widetilde{b}(t-T)}(a_{\varepsilon}(t) - a(t))Au(t) - e^{\widetilde{b}(t-T)}a_{\varepsilon}(t)(\widetilde{A}_{\varepsilon} - A)u(t).$$
(19)

By taking the inner product (19) with  $z_{\varepsilon}(t)$ , we get

$$\langle z_{\varepsilon}'(t) + a_{\varepsilon}(t)\widetilde{A}_{\varepsilon}z_{\varepsilon}(t) - \widetilde{b}z_{\varepsilon}(t), z_{\varepsilon}(t) \rangle = \left\langle e^{\widetilde{b}(t-T)} \Big[ f(t, v_{\varepsilon}(t)) - f(t, u(t)) \Big], z_{\varepsilon}(t) \right\rangle - e^{\widetilde{b}(t-T)} \left\langle (a_{\varepsilon}(t) - a(t))Au(t), z_{\varepsilon}(t) \right\rangle - e^{\widetilde{b}(t-T)} \left\langle (\widetilde{A}_{\varepsilon} - A)u(t), z_{\varepsilon}(t) \right\rangle.$$
(20)

A direct computation implies that

$$\frac{d}{dt} \| z_{\varepsilon}(t) \|_{H}^{2} = 2 \langle -a_{\varepsilon}(t) \widetilde{A}_{\varepsilon} z_{\varepsilon}(t), z_{\varepsilon}(t) \rangle + 2 \widetilde{b} \langle z_{\varepsilon}(t), z_{\varepsilon}(t) \rangle 
+ 2 \langle e^{\widetilde{b}(t-T)} [f(t, v_{\varepsilon}(t)) - f(t, u(t))], z_{\varepsilon}(t) \rangle 
- 2 e^{\widetilde{b}(t-T)} \langle (a_{\varepsilon}(t) - a(t)) A u(t), z_{\varepsilon}(t) \rangle 
- 2 e^{\widetilde{b}(t-T)} \langle (\widetilde{A}_{\varepsilon} - A) u(t), z_{\varepsilon}(t) \rangle 
= 2 (\widetilde{I}_{1} + \widetilde{I}_{2} + \widetilde{I}_{3} + \widetilde{I}_{4}),$$
(21)

where

$$\begin{split} \widetilde{I_1} &= \langle -a_{\varepsilon}(t)\widetilde{A}_{\varepsilon}z_{\varepsilon}(t), z_{\varepsilon}(t) \rangle + \widetilde{b}\langle z_{\varepsilon}(t), z_{\varepsilon}(t) \rangle, \\ \widetilde{I_2} &= \langle e^{\widetilde{b}(t-T)} \Big[ f_{\varepsilon}(t, v_{\varepsilon}(t)) - f(t, u(t)) \Big], z_{\varepsilon}(t) \rangle, \\ \widetilde{I_3} &= -e^{\widetilde{b}(t-T)} \langle (a_{\varepsilon}(t) - a(t))Au(t), z_{\varepsilon}(t) \rangle, \\ \widetilde{I_4} &= -e^{\widetilde{b}(t-T)} \langle (\widetilde{A}_{\varepsilon} - A)u(t), z_{\varepsilon}(t) \rangle. \end{split}$$

Since  $Q = \sup_{t \in [0,T]} |a_{\varepsilon}(t)|$ , we have

$$\begin{aligned} \left| \left\langle -a_{\varepsilon}(t)\widetilde{A}_{\varepsilon}z_{\varepsilon}(t), z_{\varepsilon}(t) \right\rangle \right| &\leq \sup_{t \in [0,1]} \left| a_{\varepsilon}(t) \right| \left\| \widetilde{A}_{\varepsilon}z_{\varepsilon}(t) \right\|_{H} \left\| z_{\varepsilon}(t) \right\|_{H} \\ &\leq Q \frac{1}{QT} \ln \left( \frac{1}{\varepsilon} \right) \left\| z_{\varepsilon}(t) \right\|_{H}^{2} \\ &\leq \frac{1}{T} \ln \left( \frac{1}{\varepsilon} \right) \left\| z_{\varepsilon}(t) \right\|_{H}^{2}, \end{aligned}$$

which gives

$$\langle -a_{\varepsilon}(t)\widetilde{A}_{\varepsilon}z_{\varepsilon}(t), z_{\varepsilon}(t)\rangle \geq -\frac{1}{T}\ln\left(\frac{1}{\varepsilon}\right)\left\|z_{\varepsilon}(t)\right\|_{H}^{2}.$$

Then the term  $\widetilde{I_1}$  is estimated by

$$\widetilde{I}_{1} = \langle -a_{\varepsilon}(t)\widetilde{A}_{\varepsilon}z_{\varepsilon}(t), z_{\varepsilon}(t) \rangle + \widetilde{b}\langle z_{\varepsilon}(t), z_{\varepsilon}(t) \rangle$$

$$\geq -\frac{1}{T}\ln\left(\frac{1}{\varepsilon}\right) \left\| z_{\varepsilon}(t) \right\|_{H}^{2} + \widetilde{b} \left\| z_{\varepsilon}(t) \right\|_{H}^{2}.$$
(22)

Using Lemma 1 and noting that  $f(s, u(s)) = f_{\varepsilon}(s, u(s))$  for  $\varepsilon > 0$  small enough,  $M_{\varepsilon} \ge \sup_{t \in [0,T]} ||u(t)||$ , we have the following estimate

$$\widetilde{I}_{2} = \left\langle e^{-\widetilde{b}(T-t)} \Big[ f_{\varepsilon}(t, v_{\varepsilon}(t)) - f(t, u(t)) \Big], z_{\varepsilon}(t) \right\rangle$$

$$= e^{-2\widetilde{b}(T-t)} \left\langle f_{\varepsilon}(v_{\varepsilon}(t), t) - f_{\varepsilon}(t, u(t)), v_{\varepsilon}(t) - u(t) \right\rangle$$

$$\geq -k_{\varepsilon} e^{-2\widetilde{b}(T-t)} \left\| v_{\varepsilon}(t) - u(t) \right\|_{H}^{2}$$

$$= -k_{\varepsilon} \left\| z_{\varepsilon} \right\|_{H}^{2}.$$
(23)

Employing Hölder inequality, we can bound  $\widetilde{I}_3$  as follows

$$\widetilde{I}_{3} = \langle e^{-b(T-t)}(a_{\varepsilon}(t) - a(t))Au(t), z_{\varepsilon}(t) \rangle 
\leq e^{-2\widetilde{b}(T-t)} |a_{\varepsilon}(t) - a(t)|^{2} ||Au(t)||_{H}^{2} + ||z_{\varepsilon}(t)||_{H}^{2} 
\leq e^{-2\widetilde{b}(T-t)} |a_{\varepsilon}(t) - a(t)|^{2} \left( \sum_{n=1}^{\infty} \lambda_{n}^{2} |\langle u(t), \phi_{n} \rangle|^{2} \right) + ||z_{\varepsilon}(t)||_{H}^{2} 
\leq e^{-2\widetilde{b}(T-t)} |a_{\varepsilon}(t) - a(t)|^{2} \left( \sum_{n=1}^{\infty} \frac{1}{Q^{2}T^{2}} e^{2QT\lambda_{n}} |\langle u(t), \phi_{n} \rangle|^{2} \right) + ||z_{\varepsilon}(t)||_{H}^{2} 
\leq \frac{e^{-2\widetilde{b}(T-t)} \varepsilon^{2} E_{Q}^{2}}{QT} + ||z_{\varepsilon}(t)||_{H}^{2}.$$
(24)

Using Hölder inequality again,  $\widetilde{I}_4$  can be bounded as

$$\widetilde{I}_{4} = \langle e^{-\widetilde{b}(T-t)} a_{\varepsilon}(t) (\widetilde{A}_{\varepsilon}(t) - A(t)) u(t), z_{\varepsilon}(t) \rangle \\
\leq e^{-2\widetilde{b}(T-t)} |a_{\varepsilon}(t)|^{2} \left\| (\widetilde{A}_{\varepsilon} - A) u(t) \right\|_{H}^{2} + \left\| z_{\varepsilon}(t) \right\|_{H}^{2} \\
\leq e^{-2\widetilde{b}(T-t)} |a_{\varepsilon}(t)|^{2} \sum_{n=1}^{\infty} \left| \frac{1}{QT} \ln \left( \frac{1}{\varepsilon + e^{-QT\lambda_{n}}} \right) - \frac{1}{QT} \ln(e^{QT\lambda_{n}}) \right|^{2} |\langle u(t), \phi_{n} \rangle|^{2} \\
+ \left\| z_{\varepsilon}(t) \right\|_{H}^{2} \\
\leq e^{-2\widetilde{b}(T-t)} |a_{\varepsilon}(t)|^{2} \frac{1}{Q^{2}T^{2}} \sum_{n=1}^{\infty} \left| \ln \left( \frac{1}{\varepsilon e^{QT\lambda_{n}} + 1} \right) \right|^{2} |\langle u(t), \phi_{n} \rangle|^{2} + \left\| z_{\varepsilon}(t) \right\|_{H}^{2} \\
\leq \frac{1}{T^{2}} e^{-2\widetilde{b}(T-t)} \sum_{n=1}^{\infty} \ln^{2} \left( \varepsilon e^{QT\lambda_{n}} + 1 \right) |\langle u(t), \phi_{n} \rangle|^{2} + \left\| z_{\varepsilon}(t) \right\|_{H}^{2} \\
\leq \frac{1}{T^{2}} e^{-2\widetilde{b}(T-t)} \varepsilon^{2} \sum_{n=1}^{\infty} e^{2QT\lambda_{n}} |\langle u(t), \phi_{n} \rangle|^{2} + \left\| z_{\varepsilon}(t) \right\|_{H}^{2} \\
\leq \frac{1}{T^{2}} e^{-2\widetilde{b}(T-t)} \varepsilon^{2} E_{Q}^{2} + \left\| z_{\varepsilon}(t) \right\|_{H}^{2}.$$
(25)

Thus, (21), (22), (23), (24) and (25) yields

$$\frac{d}{dt} \| z_{\varepsilon}(t) \|_{H}^{2} \geq \left( -\frac{2}{T} \ln\left(\frac{1}{\varepsilon}\right) + 2\widetilde{b} - 2k_{\varepsilon} - 4 \right) \| z_{\varepsilon}(t) \|_{H}^{2} -2e^{-2\widetilde{b}(T-t)} \varepsilon^{2} E_{Q}^{2} \left( \frac{1}{QT} + \frac{1}{T} \right).$$
(26)

Since  $b = \frac{1}{T} \ln\left(\frac{1}{\varepsilon}\right)$  we obtain

$$\frac{d}{dt} \left\| z_{\varepsilon}(t) \right\|_{H}^{2} \geq (-2k_{\varepsilon} - 4) \left\| z_{\varepsilon}(t) \right\|_{H}^{2} - 2\varepsilon^{2} E_{Q}^{2} \left( \frac{1}{QT} + \frac{1}{T} \right)$$

Integrating the above inequality from t to T, we get

$$\begin{aligned} \left\| z_{\varepsilon}(T) \right\|_{H}^{2} &- \left\| z_{\varepsilon}(t) \right\|_{H}^{2} \geq (-2k_{\varepsilon} - 4) \int_{t}^{T} \left\| z_{\varepsilon}(s) \right\|_{H}^{2} ds \\ &- 2E_{Q}^{2} \varepsilon^{2} \left( \frac{1}{QT} + \frac{1}{T} \right) (T - t). \end{aligned}$$

Since  $\left\| z_{\varepsilon}(T) \right\|_{H}^{2} = \left\| \varphi_{\varepsilon} - \varphi \right\| \le \varepsilon$ , we have

$$\left\|z_{\varepsilon}(t)\right\|_{H}^{2} \leq (2k_{\varepsilon}+4) \int_{t}^{1} \left\|z_{\varepsilon}(s)\right\|_{H}^{2} ds + 2E_{Q}^{2} \varepsilon^{2} \left(\frac{1}{Q}+1\right) + \varepsilon^{2}.$$

This implies that

$$e^{-2\widetilde{b}(T-t)} \left\| v_{\varepsilon}(t) - u(t) \right\|_{H}^{2} \leq (2k_{\varepsilon} + 4) \int_{t}^{T} e^{-2\widetilde{b}(T-s)} \left\| v_{\varepsilon}(s) - u(s) \right\|_{H}^{2} ds$$
$$+ 2E_{Q}^{2} \varepsilon^{2} \left( \frac{1}{Q} + 1 \right) + \varepsilon^{2}.$$

Multiplying bothside to  $e^{2\tilde{b}T}$ , we obtain

$$e^{2\widetilde{b}t} \|v_{\varepsilon}(t) - u(t)\|_{H}^{2} \leq (2k_{\varepsilon} + 4) \int_{t}^{T} e^{2bs} \|v_{\varepsilon}(s) - u(s)\|_{H}^{2} ds$$
$$+ 2E_{Q}^{2} \left(\frac{1}{Q} + 1\right).$$

Applying Grönwall's inequality, we get

$$e^{2\widetilde{b}t} \left\| v_{\varepsilon}(t) - u(t) \right\|_{H}^{2} \leq 2E_{Q}^{2} \left( \frac{1}{Q} + 1 \right) e^{\int_{t}^{T} (2k_{\varepsilon} + 4)ds},$$

or

$$e^{2\widetilde{b}t} \left\| v_{\varepsilon}(t) - u(t) \right\|^2 \leq 2E_Q^2 \left( \frac{1}{Q} + 1 \right) e^{(2k_{\varepsilon} + 4)(T-t)}.$$

Hence

$$\left\| v_{\varepsilon}(t) - u(t) \right\|_{H}^{2} \leq 2E_{Q}^{2} \left( \frac{1}{Q} + 1 \right) e^{(2k_{\varepsilon} + 4)(T-t)} e^{-\frac{2t}{T} \ln\left(\frac{1}{\varepsilon}\right)}.$$

In particular, if  $t \in [t_{\varepsilon}, T]$  then

$$\begin{split} \|W^{\varepsilon}(t) - u(t)\| &= \|v_{\varepsilon}(t) - u(t)\| \leq E_{\mathcal{Q}} \sqrt{2\left(\frac{1}{\mathcal{Q}} + 1\right)} e^{2T} e^{k_{\varepsilon}T} \varepsilon^{\frac{t}{T}} \\ &\leq E_{\mathcal{Q}} \sqrt{2\left(\frac{1}{\mathcal{Q}} + 1\right)} e^{2T} \varepsilon^{\frac{t}{2T}} \\ &\leq E_{\mathcal{Q}} \sqrt{2\left(\frac{1}{\mathcal{Q}} + 1\right)} e^{2T} \frac{2T \ln(\ln(\varepsilon^{-1}))}{\ln(\varepsilon^{-1})}, \end{split}$$

where we have used (11).

Let us now consider  $t \in [0, t_{\varepsilon}]$ . One has

$$||W^{\varepsilon}(t) - u(t)|| = ||v_{\varepsilon}(t_{\varepsilon}) - u(t)|| \le ||v_{\varepsilon}(t_{\varepsilon}) - u(t_{\varepsilon})|| + ||u(t_{\varepsilon}) - u(t)||.$$

Due to the continuity, we get for  $\varepsilon$  small enough

$$\|u(t_{\varepsilon})-u(t)\| = \left\|\int_{t}^{t_{\varepsilon}} u_{t}(s)ds\right\| \leq \int_{0}^{t_{\varepsilon}} \|u_{t}(s)\| ds \leq E_{Q}t_{\varepsilon}.$$

Thus, for  $t \in [0, t_{\varepsilon}]$ ,

$$\begin{split} \|W^{\varepsilon}(t) - u(t)\| &\leq E_{Q} \sqrt{2\left(\frac{1}{Q} + 1\right)} e^{2T} \varepsilon^{\frac{t_{\varepsilon}}{2T}} + E_{Q} t_{\varepsilon} \\ &\leq 2E_{Q} \sqrt{2\left(\frac{1}{Q} + 1\right)} e^{2T} \min\left\{\varepsilon^{\frac{t}{2T}}, \frac{2T \ln(\ln(\varepsilon^{-1}))}{\ln(\varepsilon^{-1})}\right\}. \end{split}$$

This completes the proof of Theorem 3.

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