

Reduced basis methods for nonlinear ill-posed inverse problems

Dominik Garmatter

`garmatter@math.uni-frankfurt.de`

Group for Numerics of Partial Differential Equations, Goethe University Frankfurt,
Germany

Joint work with Bastian Harrach and Bernard Haasdonk

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Introduction

The forward problem

Consider

$$\nabla \cdot (\sigma(x) \nabla u(x)) = 1, \quad x \in \Omega := (0, 1)^2, \quad u(x) = 0, \quad x \in \partial\Omega.$$

Assume: σ is piecewise constant $\rightsquigarrow \sigma(x) = \sum_{q=1}^p \sigma_q \chi_{\Omega_q}(x)$.

Forward operator

$F: \mathcal{P} \subset \mathbb{R}^p \rightarrow X \subset H_0^1(\Omega)$, $\sigma \mapsto u^\sigma$, the **detailed solution**, solving

$$b(u^\sigma, v; \sigma) = f(v), \quad \text{for all } v \in X, \quad \text{with} \quad (1a)$$

$$b(u, w; \sigma) := \int_{\Omega} \sigma \nabla u \cdot \nabla w \, dx, \quad f(v) := - \int_{\Omega} v \, dx. \quad (1b)$$

Inverse Problem

For given solution $u \in X$ of (1), find corresponding parameter $\sigma^+ \in \mathcal{P}$ with $F(\sigma^+) = u$ („a-example“).

Task: Given u^δ , $\|u - u^\delta\|_X \leq \delta$, $\delta > 0$, find approximation σ^δ to σ^+ .

Nonlinear Landweber iteration

- ▶ $\sigma_{n+1}^\delta := \sigma_n^\delta + \omega F'(\sigma_n^\delta)^*(u^\delta - F(\sigma_n^\delta))$
- ▶ Terminate as $\|F(\sigma_n^\delta) - u^\delta\|_X \leq \tau\delta$ (discrepancy principle)

↪ **Many-query setting**

The reduced problem & Properties

Reduced basis (RB) space: for given *carefully* selected *snapshots* $\phi_i = F(\sigma_i)$, define $X_N := \text{span}\{\Phi_N\} = \text{span}\{\phi_1, \dots, \phi_N\}$.

Reduced forward operator

$F_N: \mathcal{P} \rightarrow X_N, \sigma \mapsto u_N^\sigma$ with u_N^σ , the **reduced solution**, solving

$$b(u_N^\sigma, v; \sigma) = f(v), \quad \forall v \in X_N.$$

- ▶ **Certification:** $\|u^\sigma - u_N^\sigma\|_X \leq \Delta_N(\sigma) := \frac{\|v_r\|_X}{\alpha(\sigma)}$,
with $\langle v_r, v \rangle_X := r(v; \sigma) := f(v) - b(u_N^\sigma, v; \sigma), \forall v \in X$
- ▶ **Offline/online decomposition:** rapid computation of u_N^σ
- ▶ **Reproduction of solutions:** $u^\sigma \in X_N \Rightarrow u_N^\sigma = u^\sigma$

RBM and Inverse problems

G./Haasdonk/Harrach, A Reduced Basis Landweber method for nonlinear inverse problems, 2016 Inverse Problems 32 (3) (doi).

RBM & Landweber method - Various approaches

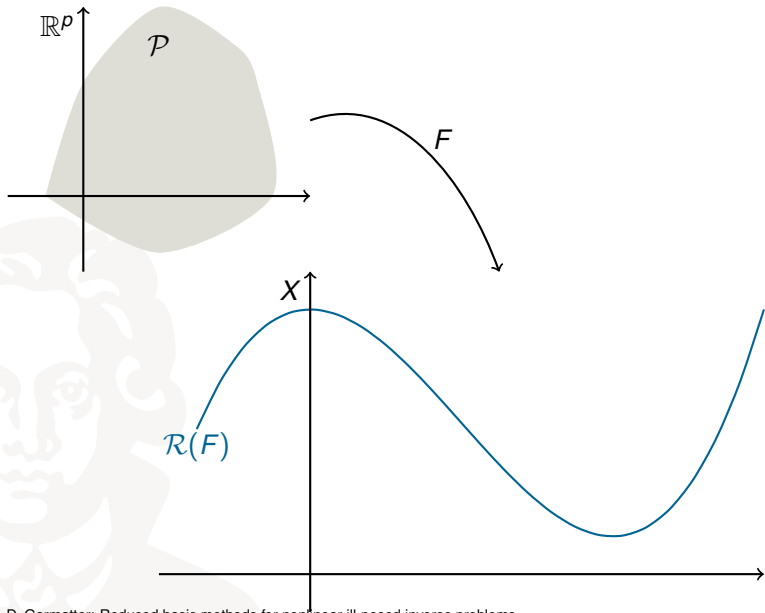
Naive approach

- ▶ Construct **global** X_N approximating whole $\mathcal{R}(F)$ (**offline-phase**)
- ▶ Rapidly compute $F_N(\sigma)$ and substitute $F(\sigma)$ for $F_N(\sigma)$ in the Landweber iteration („**online-phase**“)

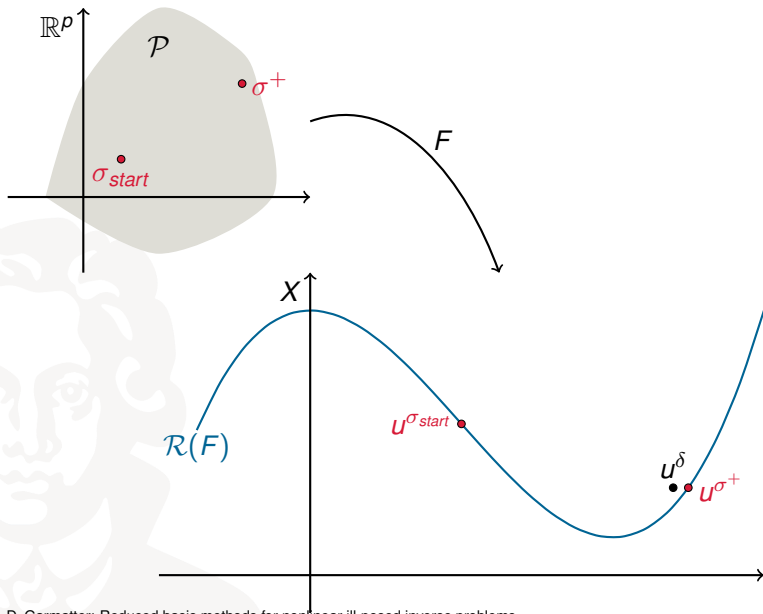
Limitation: Only feasible for low-dimensional parameter spaces, not feasible for imaging.

Our approach: Create problem-adapted RB-space by iterative enrichment (inspired by Druskin & Zaslavski 2007, Zahr & Fahrhat 2015 and Lass 2014).

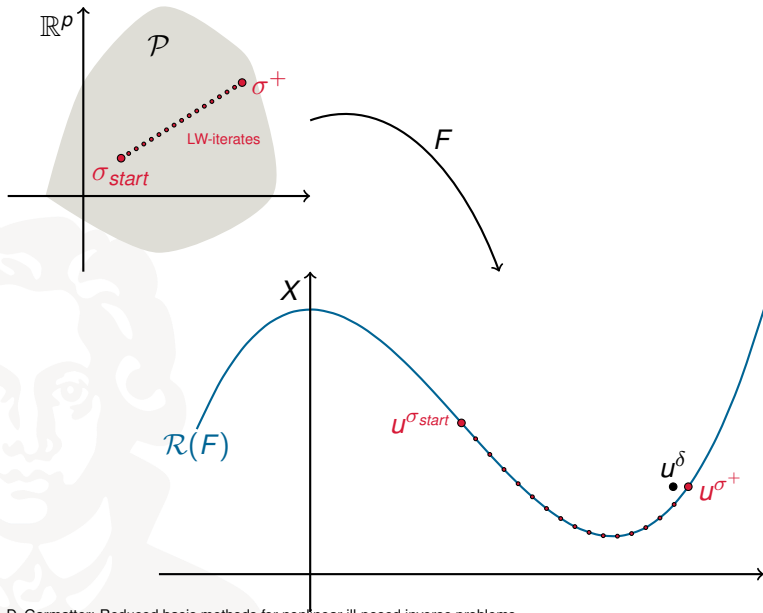
Combining RBM & LW - Idea



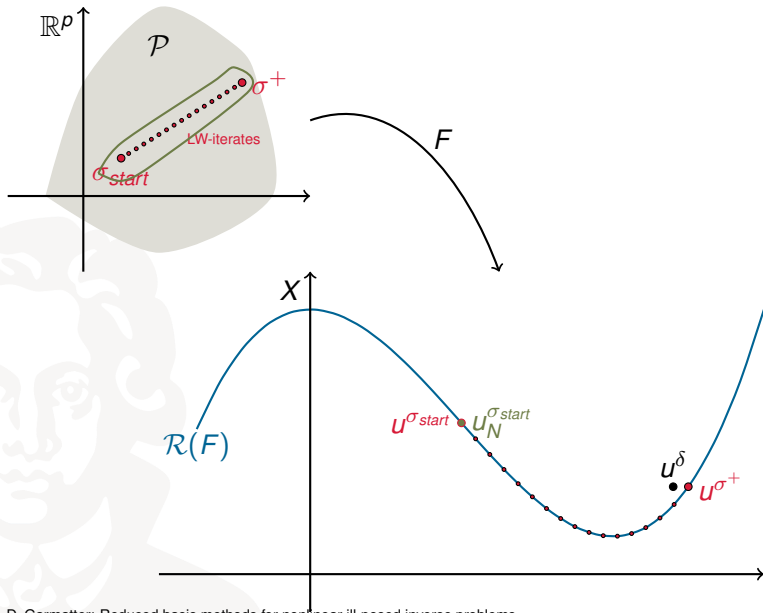
Combining RBM & LW - Idea



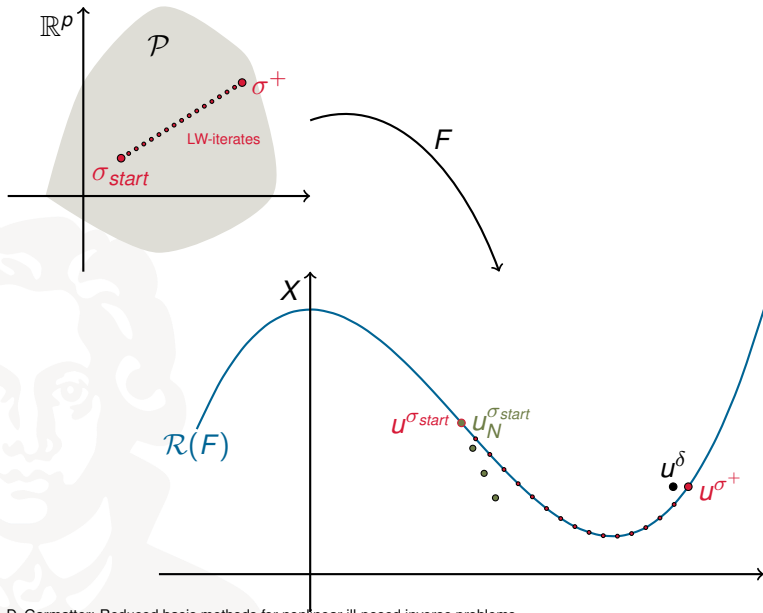
Combining RBM & LW - Idea



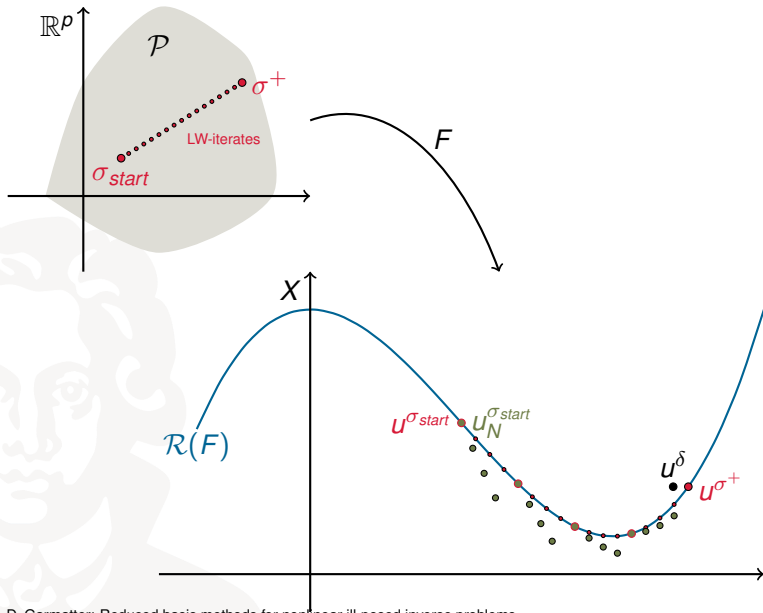
Combining RBM & LW - Idea



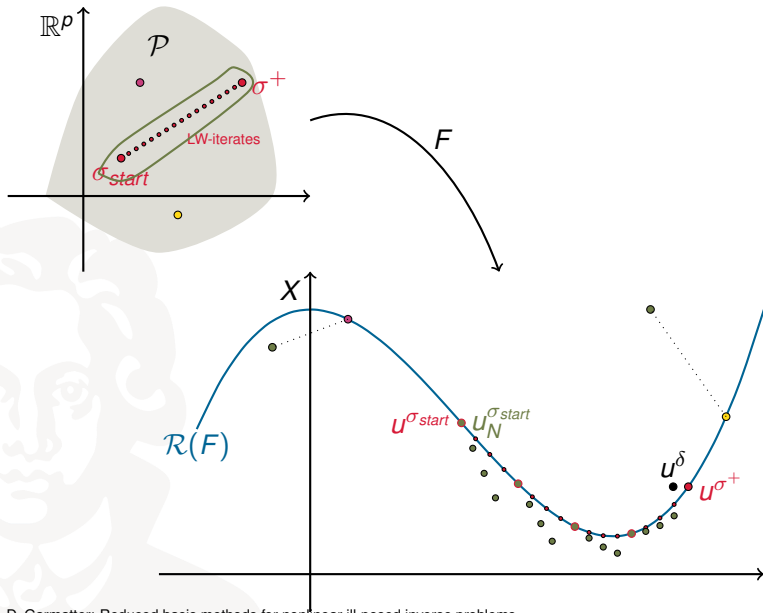
Combining RBM & LW - Idea



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Combining RBM & LW - Idea



Reduced Basis Landweber (RBL) method

Algorithm 1 RBL($\sigma_{start}, \tau, \Phi_N$)

```

1:  $n := 0, \sigma_0^\delta := \sigma_{start}$ 
2: while  $\|F(\sigma_n^\delta) - u^\delta\|_X > \tau\delta$  do
3:   enrich RB using  $\sigma_n^\delta$ 
4:    $i := 1, \sigma_i^\delta := \sigma_n^\delta$ 
5:   repeat
6:     calculate reduced Landweber update  $s_{n,i}$ 
7:      $\sigma_{i+1}^\delta := \sigma_i^\delta + \omega s_{n,i}$ 
8:      $i := i + 1$ 
9:   until  $\|F_N(\sigma_i^\delta) - u^\delta\|_X \leq \tau\delta$  or  $\Delta_N(\sigma_i^\delta) > (\tau - 2)\delta$ 
10:   $\sigma_{n+1}^\delta := \sigma_i^\delta$ 
11:   $n := n + 1$ 
12: end while
13: return  $\sigma_{RBL} := \sigma_n^\delta$ 

```

Numerics - compare reconstructions

Setting: $\rho = 900$, $\tau = 2.5$, $\delta = 1\%$ and $\omega = \frac{1}{2}(\|F'(\sigma_{start})\|)^{-1}$.

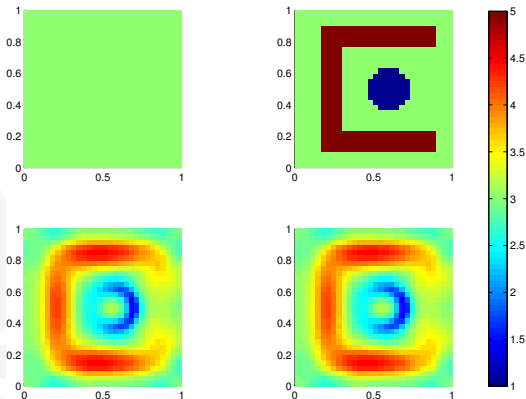


Figure: σ_{start} (top left), exact solution σ^+ (top right). Reconstruction via RBL method (bottom left) and Landweber method (bottom right).

Numerics - time comparison

- ▶ **Outer iteration:** space enrichment, projection („offline“)
- ▶ **Inner iteration:** one iteration of repeat loop („online“)

Algorithm	Landweber	RBL	
time (s)	187189	14661	
# Iterations	608067	outer	20
		inner	608083
time per Iteration (s)	0.308	outer	3.705
		inner	0.024
# forward solves	1216134	40	

$$\|\sigma_{RBL} - \sigma_{LW}\|_{\mathcal{P}} \approx 1.118 \cdot 10^{-5}$$

Numerics - regularization property

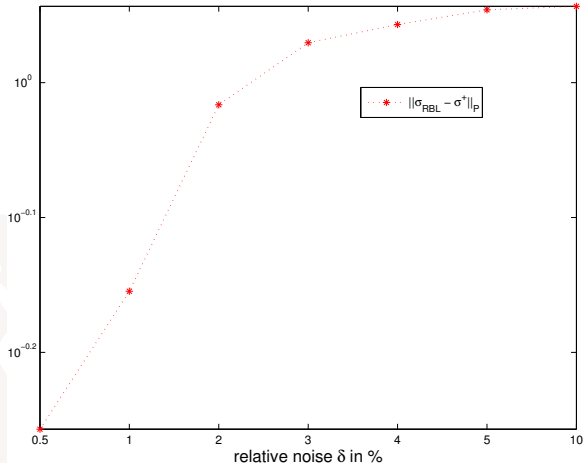


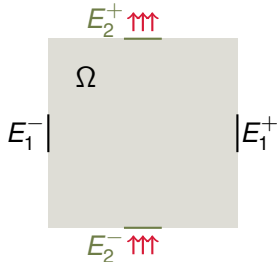
Figure: Error $\|\sigma_{RBL} - \sigma^+\|_P$ over the decreasing relative noise level δ .

Current Work

Magnet Resonance Electrical Impedance Tomography

Goal: Obtain high-resolution spatial images of conductivity σ of Ω

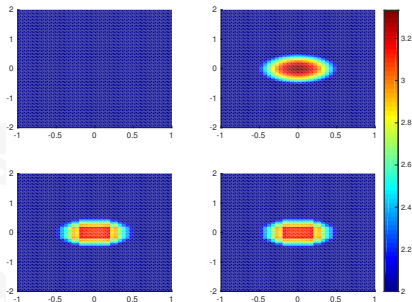
- ▶ Object Ω with electrode pairs E_1^\pm , E_2^\pm attached to it
- ▶ Apply **current** between **electrode pair** generates magnetic flux density B
 \rightsquigarrow obtainable with MRI scanner
- ▶ Use this *internal* data to overcome ill-posedness and reconstruct σ



Harmonic-Bz-Algorithm (Seo, Woo, et al. 2003)

MREIT - first numerics

Setting: 3200 pixels, ≈ 50000 FEM-dofs, no noise.



- ▶ Bz Algorithm: 3.01 s
- ▶ RBz-Algorithm: 1.79 s
- ▶ Normdifference:
 $\approx 8.33 \cdot 10^{-4}$

Figure: σ_{start} (top left), σ^+ (top right), reconstruction via Bz-Algorithm (bottom left) and RBz-Algorithm (bottom right).

Conclusion

- ▶ Solving inverse coefficient problem requires many PDE solves
- ▶ Reduced basis (RB) approach can speed up PDE solution
- ▶ But standard RB approach is only applicable for low dimensional parameter spaces
- ▶ Using adaptive problem-specific RB enrichment, we can handle high-dimensional parameter spaces, e.g. for imaging problems

↪ RBL method outperforms standard Landweber
(exp.: 13 times faster without loss of accuracy)

- ▶ Finalize theory and numerics for MREIT-project

Thank you for your attention!



Appendix

Appendix - The dual problem

$$\text{Recall } \sigma_{n+1}^\delta := \sigma_n^\delta + \omega F'(\sigma_n^\delta)^*(u^\delta - F(\sigma_n^\delta))$$

For $\sigma, \kappa \in \mathcal{P}$ and $l \in X$, one can show

$$\langle \kappa, F'(\sigma)^* l \rangle_{\mathcal{P}} = \int_{\Omega} \kappa \nabla u^\sigma \cdot \nabla u_l^\sigma \, dx, \quad (2)$$

with $u_l^\sigma \in X$ the unique solution of the **dual problem**

$$b(u, v; \sigma) = m(v; l), \text{ for all } v \in X, \quad m(v; l) := - \int_{\Omega} l v \, dx.$$

In Algorithm 1 \rightsquigarrow **two RB spaces** $X_{N,1}, X_{N,2}$

- ▶ enrich $X_{N,1}$ via $F(\sigma_n^\delta)$ and $X_{N,2}$ via $u_l^{\sigma_n^\delta}$ with $l := u^\delta - F(\sigma_n^\delta)$
- ▶ calculate $s_{n,i}$ using (2) and associated reduced solutions