

COMPLETELY PERIODIC DIRECTIONS AND ORBIT CLOSURES OF MANY PSEUDO-ANOSOV TEICHMUELLER DISCS IN $Q(1,1,1,1)$

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ABSTRACT. In this paper, we investigate the closure of a large class of Teichmüller discs in the stratum $Q(1, 1, 1, 1)$ or equivalently, in a $GL_2^+(\mathbb{R})$ -invariant locus \mathcal{L} of translation surfaces of genus three. We describe a systematic way to prove that the $GL_2^+(\mathbb{R})$ -orbit closure of a translation surface in \mathcal{L} is the whole locus \mathcal{L} . The strategy of the proof is an analysis of completely periodic directions on such a surface and an iterated application of Ratner's theorem to unipotent subgroups acting on an "adequate" splitting.

This analysis applies for example to all Teichmüller discs obtained by the Thurston-Veech construction with a trace field of degree three which are moreover "obviously not Veech".

We produce an infinite series of such examples and show moreover that the favourable splitting situation does not arise everywhere on \mathcal{L} , contrary to the situation in genus two.

We also study completely periodic directions on translation surfaces in \mathcal{L} . For instance, we prove that completely periodic directions are dense on surfaces obtained by the Thurston-Veech construction.

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Date: October 20, 2008.

2000 Mathematics Subject Classification. Primary: 32G15. Secondary: 30F30, 57R30, 37D40.

Key words and phrases. Abelian differential, Veech group, Pseudo-Anosov diffeomorphism, Teichmüller disc, orbit closures.

INTRODUCTION

For translation surfaces in genus two, $\mathrm{GL}_2^+(\mathbb{R})$ -orbit closures, completely periodic translation surfaces and many more properties have been classified by Calta, McMullen and e.g. [EMS03], [HLe06]. For half-translation surfaces, i.e. for pairs (X, q) of a Riemann surface and a quadratic differential, as well as for surfaces of genus $g \geq 3$ the situation is much more complicated. At present, all classification questions are open. In [HLM06] and in the present paper, we study translation surfaces belonging to \mathcal{L} , the hyperelliptic locus of the non hyperelliptic connected component of the stratum $\mathcal{H}(2, 2)$ (the moduli space of Abelian differentials having two double zeroes). The locus \mathcal{L} is closed and $\mathrm{GL}_2^+(\mathbb{R})$ -invariant. It is more natural to study \mathcal{L} than it sounds on a first reading since it is $\mathrm{GL}_2^+(\mathbb{R})$ -equivariantly isomorphic to $\mathcal{Q}(1, 1, 1, 1)$, the principal stratum of quadratic differentials in genus 2. We are thus studying the next simplest cases besides translation surfaces in genus two. Let us note that for two other strata, $\mathcal{Q}(2, 2)$ and $\mathcal{Q}(2, 1, 1)$ some properties of closed $\mathrm{GL}_2^+(\mathbb{R})$ -orbits, namely the arithmeticity of Veech surfaces, have been obtained in [Vas05].

Projections of $\mathrm{GL}_2^+(\mathbb{R})$ -orbits of translation surfaces to Teichmüller space give rise to Teichmüller discs. The setwise stabilizer of a Teichmüller disc in the mapping class group is a subgroup of $\mathrm{SL}_2(\mathbb{R})$, that reflects the geometry of the original translation surface. See Section 1 for details on the basic notions and references.

We focus in this paper on Teichmüller discs that are stabilized by a pseudo-Anosov diffeomorphism (pseudo-Anosov Teichmüller discs or pseudo-Anosov translation surfaces, for short). The Arnoux-Yoccoz example ([AY81], [Arn88]) is a pseudo-Anosov Teichmüller disc with many very exotic properties. In [HLM06], we proved that the $\mathrm{GL}_2^+(\mathbb{R})$ -orbit closure of the Arnoux-Yoccoz Teichmüller disc is the whole locus \mathcal{L} . Rephrasing the previous result in the language of quadratic differentials, we proved the existence of a pseudo-Anosov Teichmüller disc with a dense $\mathrm{GL}_2^+(\mathbb{R})$ -orbit in $\mathcal{Q}(1, 1, 1, 1)$. This is very different from the behavior described by McMullen for Abelian differentials in genus 2: every pseudo-Anosov disc is contained in the eigenform locus over a Hilbert modular surface.

In this paper, we describe a systematic way to prove that the $\mathrm{GL}_2^+(\mathbb{R})$ -orbit closure of a surface in \mathcal{L} is the whole locus \mathcal{L} . This analysis applies to a large family of pseudo-Anosov Teichmüller discs obtained by the Thurston-Veech construction (see [Thu88, Vee89]). Recall that a direction is completely periodic on a translation surface if the surface is decomposed into a union of cylinders in this direction. We have

Theorem 0.1. *Let $(X, \omega) \in \mathcal{L}$ be a surface given by the Thurston-Veech construction with trace field of degree 3. Let us assume that (X, ω) is not a Veech surface for the most obvious*

reason: there exists a completely periodic direction which is not parabolic. Then

$$\overline{\mathrm{GL}_2^+(\mathbb{R}) \cdot (X, \omega)} = \mathcal{L}.$$

Without the trace field condition the statement is false. Counterexamples are given by translation surfaces that arise as coverings from genus one or genus two.

Of course, by the ergodicity of the geodesic flow on any stratum, the $\mathrm{GL}_2^+(\mathbb{R})$ -orbit closure of a generic surface in \mathcal{L} equals \mathcal{L} . While pseudo-Anosov Teichmüller discs as in the theorem above behave like generic surfaces, they have quite remarkable topological properties. Without restrictions on the trace field we show:

Theorem 0.2. *Let $(X, \omega) \in \mathcal{L}$ be a surface stabilized by a pseudo-Anosov diffeomorphism. Let us assume that there exists a completely periodic direction. Then the set of completely periodic directions on (X, ω) is a dense subset of the circle \mathbb{S}^1 .*

Obviously, the conclusion fails for a generic surface in \mathcal{L} , see Proposition 3.4. Note that the last result applies to translation surfaces given by the Thurston-Veech construction. Combining these last two theorems, one gets:

Theorem 0.3. *Let $(X, \omega) \in \mathcal{L}$ be a surface given by the Thurston-Veech construction with trace field of degree 3. Then at least one of the following holds:*

- (1) *The closure of the orbit $\mathrm{GL}_2^+(\mathbb{R}) \cdot (X, \omega)$ is the whole locus \mathcal{L} .*
- (2) *The limit set of the Veech group $\mathrm{SL}(X, \omega)$ is the full circle.*

Remark 0.3.1. We do not know if there exists a surface which satisfies these two properties at the same time.

Our results apply to an infinite family of surfaces, for instance a series of surfaces arising from the Thurston-Veech construction.

Reader's guide. We end this introduction by explaining the organization of the paper and by sketching a proof of the main results.

The strategy of the proof of Theorem 0.1 is to use an “adequate irrational” splitting on a surface (Y, η) belonging to the closure of the $\mathrm{SL}_2(\mathbb{R})$ -orbit of (X, ω) . Such a splitting is given by four homologous saddle connections which decompose the surface into two fixed tori and two exchanged cylinders. We will call such a decomposition a $2T_{\mathrm{fix}}2C$ splitting. Following the strategy presented in [Mc3] and [HLM06], we conclude by applying Ratner's theorem [Rat91] to a one parameter unipotent subgroup acting on the product of the space of pairs of area 1 lattices and the space of cylinders.

We use the non parabolic completely periodic direction to obtain the surface (Y, η) by the following way. In Section 2 we describe all completely periodic configurations of surfaces in \mathcal{L} . For each of these configurations, in Section 4,

we apply Ratner's theorem to $(\mathrm{SL}_2(\mathbb{R})/\mathrm{SL}_2(\mathbb{Z}))^3$ the space of triples of normalized lattices in order to get a resplitting of (X, ω) into (Y, η) with an irrational $2T_{\mathrm{fix}}2C$. This can only work under some mild irrationality hypothesis, which will be a consequence of the trace field condition and the existence of a non-parabolic direction.

We now give a sketch of the proof of Theorem 0.2. Following Calta-Smillie [CS07], the hypothesis implies that the Sah-Arnoux-Fathi (SAF)-invariant [Arn81] is zero for every direction of the holonomy field. Given a direction θ containing a cylinder fixed by the hyperelliptic involution, we remove this cylinder from the surface and obtain a genus 2 translation surface Y with boundary. Using the fact that the SAF-invariant vanishes on Y and the list of periodic configuration given in Section 2, we prove that the flow is periodic in the direction θ on Y .

In Section 6, we check the hypothesis of Theorem 0.1 for an infinite family of examples arising from the Thurston-Veech construction.

In the last section, we briefly discuss the existence of a $2T_{\mathrm{fix}}2C$ splitting on surfaces belonging to \mathcal{L} .

Acknowledgments. We thank C. McMullen for comments on preliminary versions of this article and E. Nipper for a careful reading. This work was partially supported by the ANR Teichmüller "projet blanc" ANR-06-BLAN-0038 and by the Max-Planck Institut für Mathematik, Bonn.

1. BACKGROUND

In this section we review basic notions concerning translation surfaces, trace fields, J -invariant and SAF-invariant.

A *translation surface* (or *flat surface*) is a Riemann surface X with finitely many *singularities* P_i , plus the choice of charts covering $X \setminus \{P_i\}$, such that the transition functions are translations. Equivalently, a translation surface is given by a pair (X, ω) of a Riemann surface X and a holomorphic one-form ω . For *half-translation surfaces* the conditions are relaxed to demanding the transition functions to be $\pm \mathrm{id}$ composed with a translation. Equivalently, half-translation surfaces are given by a pair (X, q) of a Riemann surface X and a quadratic differential q .

A half-translation surface admits a ramified double covering, which is a translation surface and except for the introduction we will work exclusively with translation surfaces. Translation surfaces correspond bijectively to pairs (X, ω) of a Riemann surface X and a holomorphic one-form. Similarly, half-translation surfaces correspond bijectively to pairs (X, q) , where q is a quadratic differential. See e.g. [MT02] for a survey on these notions. The singularities correspond to the zeros of ω resp. of q under this bijection.

There is a natural action of $GL_2^+(\mathbb{R})$ on (half-) translation surfaces by post-composing the integration charts with the corresponding linear map. This action respects the number and multiplicities of zeros, called the *signature*, of the one-form (resp. the quadratic differential). Consequently the moduli space of pairs (X, ω) (respectively of pairs (X, q)), denoted by \mathcal{H} , by some authors also by ΩM_g (respectively \mathcal{Q} , sometimes QM_g) is stratified by the signature. The stratum $\mathcal{H}(2, 2)$ has two connected components (see [KZ03]). One component is the hyperelliptic component. The locus \mathcal{L} is a codimension 1 subspace of the non hyperelliptic component of the stratum $\mathcal{H}(2, 2)$.

Straight lines in the translation charts are geodesics for the metric $|\omega|$. A maximal subset of X swept out by parallel geodesics is called an (open) *cylinder*. Its closure will be bounded by a finite number of *saddle connections*, geodesics joining the singularities. We will say that a cylinder is *simple* if each of its boundaries consists of a unique saddle connection (joining possibly the two zeroes). A geodesic has a well defined direction in $\mathbb{C} \cong \mathbb{R}^2$ and the direction of a cylinder is the direction of any of its geodesics.

Consider all geodesics in a fixed direction θ . This direction is called *periodic* if there is an open cylinder in this direction. θ is called *completely periodic*, if X decomposes completely into cylinders and saddle connections in this direction. Note that there is also the notion ([Cal04]) of a *completely periodic surface* (X, ω) , a surface such that each direction that has a cylinder is automatically completely periodic. This notion will not be used in the remainder of this paper.

A completely periodic direction is called *parabolic*, if the moduli of the cylinders in this direction are commensurable. Parabolic directions are important, since a composition of suitable powers of Dehn twists along the cylinders produces a diffeomorphism which is affine with respect to the charts given by ω ([Vee89]). We denote by $\text{Aff}^+(X, \omega)$ the group of orientation-preserving affine diffeomorphisms and by $\text{SL}(X, \omega)$ its image under the natural map to $\text{SL}_2(\mathbb{R})$. This image is called *affine group* or *Veech group* of (X, ω) . It is well-known, that a diffeomorphism in $\text{Aff}^+(X, \omega)$ is pseudo-Anosov, if and only if its image in $\text{SL}(X, \omega)$ is a hyperbolic element of $\text{SL}_2(\mathbb{R})$. The *trace field* of (X, ω) is the field generated over \mathbb{Q} by the traces of all elements in $\text{SL}(X, \omega)$. One can also define the trace field by the following way. One defines the *holonomy vectors* to be the integrals of ω along the saddle connections. Let us denote by $\Lambda = \Lambda(\omega)$ the subgroup of \mathbb{R}^2 generated by holonomy vectors $\Lambda = \int_{H_1(X, \mathbb{Z})} \omega$. If $e_1, e_2 \in \Lambda$ are two nonparallel vectors in \mathbb{R}^2 , one defines the *holonomy field* k to be the smallest subfield of \mathbb{R} such that every element of Λ may be written as $ae_1 + be_2$ with $a, b \in k$. It is known ([KS00] Theorem 28) that if $\text{SL}(X, \omega)$ contains a pseudo-Anosov diffeomorphism, then the trace field of

(X, ω) coincides with k . In particular, any direction θ of saddle connection belongs to the trace field.

If P is a polygon in \mathbb{R}^2 with vertices v_1, \dots, v_n in counterclockwise order about the boundary of P , then the J -invariant of P is $J(P) = \sum_{i=1}^n v_i \wedge v_{i+1}$ (with the dummy condition $v_{n+1} = v_1$). Here \wedge is taken to mean $\wedge_{\mathbb{Q}}$ and \mathbb{R}^2 is viewed as a \mathbb{Q} -vector space. $J(P)$ is a translation invariant (e.g. $J(P + \vec{v}) = J(P)$), thus this permits to define $J(X, \omega)$ by $\sum_{i=1}^k J(P_i)$ where $P_1 \cup \dots \cup P_k$ is a cellular decomposition of (X, ω) into planar polygons (see [KS00]).

We will also make use of the SAF-invariant of an interval exchange transformation f as follows. We define a linear projection $J_{xx} : \mathbb{R}^2 \wedge_{\mathbb{Q}} \mathbb{R}^2 \rightarrow \mathbb{R} \wedge_{\mathbb{Q}} \mathbb{R}$ by

$$J_{xx} \left(\begin{pmatrix} a \\ b \end{pmatrix} \wedge \begin{pmatrix} c \\ d \end{pmatrix} \right) = a \wedge c.$$

If f is an interval exchange transformation induced by the first return map of the vertical foliation on (X, ω) (on a transverse interval I) then let us define the SAF-invariant of f by $SAF(f) = J_{xx}(X, \omega)$. Note that the definition does not depend of the choice of I if the interval meets every vertical leaf (see [Arn81]). We will also say that $SAF(f)$ is the SAF-invariant of (X, ω) in the vertical direction. We define in an obvious manner the SAF-invariant of (X, ω) in a direction of the trace field.

If f is a periodic interval exchange transformation then $SAF(f) = 0$. The converse is not true in general. But if f is defined over 2 or 3 intervals and $SAF(f) = 0$ then f is periodic.

We now sketch the Thurston-Veech construction ([Thu88], see also [Vee89]) of surfaces¹ with pseudo-Anosov diffeomorphisms. Choose a pair $(\{\gamma_i\}_{i \in I}, \{\gamma_j\}_{j \in J})$ of multicurves, i.e. of sets of simple closed curves on X such that $X \setminus (\cup_{i \in I} \gamma_i \cup \cup_{j \in J} \gamma_j)$ is a union of simply connected regions. Let $M_{r,s} = (\gamma_r, \gamma_s)$ for $r, s \in I \cup J$ be the symmetric intersection matrix. Choose integer weights m_r for $r \in I \cup J$ and let (h_r) be the unique (by Perron-Frobenius) positive eigenvector satisfying

$$\mu h_r = \sum_{s \in I \cup J} m_r M_{rs} h_s.$$

Now glue rectangles $[0, h_r] \times [0, h_s]$ according to the intersection pattern of the multicurves γ_i , $i \in I$, and γ_j , $j \in J$, to obtain a closed surface. This surface may have cone-type singularities at points corresponding to the corners of the squares.

Suitable powers of Dehn twist along the curves γ_i , $i \in I$ (resp. along the curves γ_j , $j \in J$) define two non-commuting parabolic elements in $SL(X, \omega)$. Suitable products of them give hyperbolic elements in $SL(X, \omega)$, thus the corresponding

¹Also known as *bouillabaisse surfaces*, after a talk by J.Hubbard, CIRM 2003

diffeomorphism is a pseudo-Anosov diffeomorphism. One of the main results of [HL06] shows, that not all pseudo-Anosov diffeomorphisms arise in this way.

2. CONFIGURATIONS

In this section, we classify (topologically) the configurations of completely periodic directions θ on a translation surface belonging to the hyperelliptic locus \mathcal{L} .

2.1. Statement of the result. Cut X along the set of saddle connections in the direction θ . The result is a set of cylinders. To reconstruct the surface (X, ω) , we have to glue these cylinders together according to a pattern which describes which part of one cylinder is glued which part of another cylinder. We will call this pattern a *configuration*. For instance, in Figure 1a, the configuration presented has 3 cylinders (for the vertical direction $\theta = \pi/2$). One cylinder is fixed by the involution (we have represented the Weierstrass points by small small solid circles) and the two others are exchanged. We label the intervals representing the same saddle connection on the surface by the same number. Horizontal saddle connections are identified by vertical translation. A simple computation, using the Euler characteristic, shows that the number of cylinders is bounded above by 4. In this section we will prove the following result.

Theorem 2.1. *Let (X, ω) be a translation surface in the hyperelliptic locus \mathcal{L} . Let us assume that the vertical direction is completely periodic. Then all possible configurations of cylinders are prescribed by Figure 1. More precisely:*

- (1) *There are four configurations with two cylinders:*
 - *One configuration with two exchanged cylinders corresponding to Figure 1h.*
 - *Three configurations with two fixed cylinders corresponding to Figure 1i, Figure 1j and Figure 1k.*
- (2) *There are four configurations with three cylinders:*
 - *Two configurations with one fixed cylinder corresponding to Figure 1a and Figure 1b.*
 - *Two configurations with three fixed cylinders corresponding to Figure 1c and Figure 1d.*
- (3) *There are three configurations with four cylinders:*
 - *Two configurations with two simple cylinders corresponding to Figure 1e and Figure 1f.*
 - *One configuration with one simple cylinder corresponding to Figure 1g.*

Remark 2.1.1. If (X, ω) arises from the Thurston-Veech construction and admits a one cylinder decomposition, then either $SL(X, \omega)$ is a cyclic unipotent subgroup, or $SL(X, \omega)$ is commensurable to $SL_2(\mathbb{Z})$, e.g. (X, ω) is a covering of flat torus ramified over point.

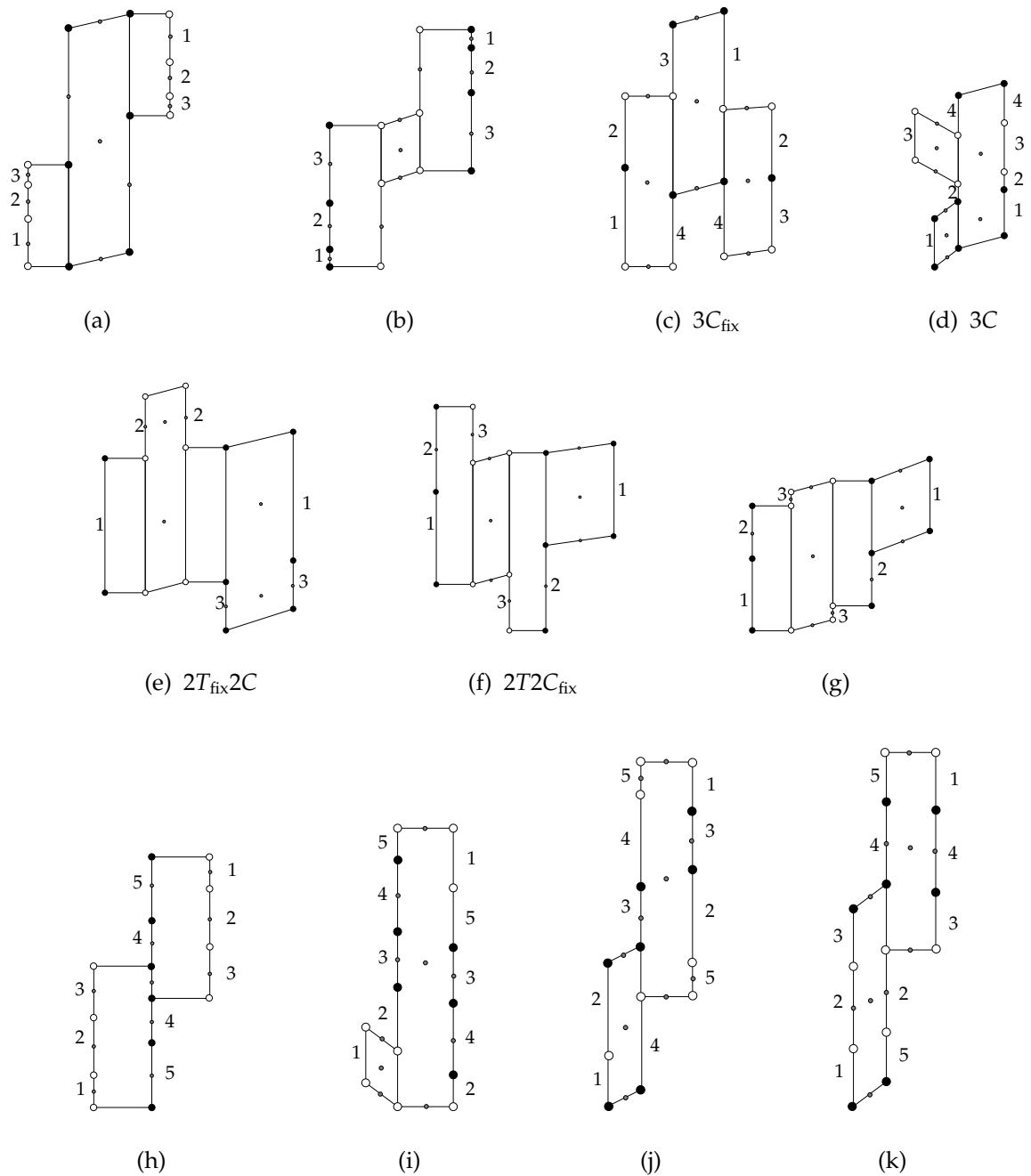


FIGURE 1. List of (topological) configurations of completely periodic surfaces in \mathcal{L} (for the vertical direction). The Weierstrass points correspond to the smallest solid circles.

We will use the following obvious lemma.

Lemma 2.2. *Let $(X, \omega) \in \mathcal{L}$ be a translation surface and let us assume that the vertical direction is completely periodic direction. Then:*

- (1) *There exist 6 saddle connections joining a zero to another zero.*
- (2) *A Weierstrass point is located either on the middle of a saddle joining a zero to itself or on the core of a cylinder. In the last case there are exactly two Weierstrass points on the core curve.*
- (3) *If no cylinder is fixed by the involution then there is no saddle connection connecting the two zeroes.*
- (4) *If exactly one cylinder is fixed by the involution then there is at most one saddle connection connecting the two zeroes.*

We will now give a proof of the main theorem of this section.

2.2. Proof of Theorem 2.1 in case of four cylinders. Let (X, ω) be a translation surface and let us assume that the vertical direction is completely periodic and decomposes the surface in four metric cylinders. Clearly the number of fixed cylinders (with respect to the hyperelliptic involution) is congruent to the total number of cylinders mod 2 so it is 0, 2 or 4. If all the cylinders are fixed then each cylinder will possess two fixed points (for the involution). Recall that the two zeroes are fixed, thus the hyperelliptic involution should possess $4 \times 2 + 2 = 10$ fixed points which is impossible.

Claim 2.3. *There are exactly two fixed cylinders.*

Proof of the Claim. Assume not. Then from above discussion, there is no fixed cylinder. Thus all the Weierstrass points (except for the two singularities) are located on the middle of the saddle connection. In particular, there is no saddle connection connecting the two zeroes.

Note that a Weierstrass point cannot be located on the boundary of a simple cylinder. Therefore there is no simple cylinder on such a configuration. Thus the only possible configuration is the following one: four cylinders, each of them having three saddle connections on its boundaries. It is then not hard to check that there is no possible configuration with 8 fixed points for the involution. The claim is proven. \square

Thus, a configuration with four cylinders must have exactly two fixed cylinders.

Claim 2.4. *The number of simple cylinders is 1 or 2.*

Proof of the Claim. Assume not. If there are four simple cylinders then obviously (X, ω) is a torus, which is impossible.

If there is no simple cylinder then the number of saddle connections is at least 8 for the two fixed cylinders and 6 for the other two. Finally the number of saddle connections is at least $8 + 6 = 14 > 12$, which is a also a contradiction. \square

Hence there is either 1 (necessarily fixed) simple cylinder, or 2 (fixed or exchanged) simple cylinders. These three possibilities lead to three configurations. It is not hard to show that the three possible cases are respectively given by Figure 1g-1f-1e. The last two configurations will be respectively called $2T2C_{\text{fix}}$ and $2T_{\text{fix}}2C$.

2.3. Proof of Theorem 2.1 in case of three cylinders. Let (X, ω) be a translation surface and let us assume that the vertical direction is completely periodic and decomposes the surface in three metric cylinders. Clearly the number of fixed cylinders (with respect to the hyperelliptic involution) is 1 or 3.

Claim 2.5. *Let us assume that only one cylinder is fixed by the involution. Then the number of simple cylinders is 0 or 1.*

Proof of the Claim. Suppose not. Then the configuration for the vertical direction must contain two or three simple cylinders. In the last case X is a torus, which is impossible.

If the configuration contains only two simple cylinders, they are necessarily exchanged. Thus each boundary of the fixed cylinder must possess exactly four saddle connections. Note that a Weierstrass point can not be located on the boundary of a simple cylinder. Let us count the number of Weierstrass points:

- (1) the two zeroes.
- (2) two Weierstrass points on the core curve of the fixed cylinder.
- (3) at most two Weierstrass points on the middle of the saddle connections of the fixed cylinder.

Thus there are at most $6 < 8$ Weierstrass points which is a contradiction. \square

Hence for such a configuration, there is no simple cylinder or one fixed simple cylinder. It is then not difficult to check that these two cases lead respectively to the configurations presented in Figure 1a and in Figure 1b.

Claim 2.6. *Let us assume that the three cylinders are fixed by the involution. Then the number of simple cylinders is 0 or 2.*

Proof of the Claim. Assume not. Then the configuration contains only one fixed simple cylinder. The Weierstrass points are located on the core curves of the cylinders; there are no Weierstrass points on the separatrices. Using this restriction, a straightforward calculation shows that no such configuration is possible in the hyperelliptic locus \mathcal{L} . \square

Thus in that case, the configuration possesses either three (non simple) fixed cylinders or two simples and one other (all fixed) cylinders. It is then easy to see that these two cases lead respectively to configurations presented in Figure 1c and in Figure 1d.

The proof of the theorem in case of two cylinders is left to the reader as an exercise.

In the following sections we will use the following characterization.

Corollary 2.7. *The $2T_{\text{fix}}2C$ -configuration is characterized as the unique configuration with 4 homologous saddle connections.*

3. COMPLETE PERIODICITY

We recall the following result by H. Masur (see [Mas86, MT02]):

Theorem 3.1 (Masur). *Let (X, ω) be a translation surface. There is a dense set of periodic directions on (X, ω) .*

In this section, we prove the following strengthening for translation surfaces in the locus \mathcal{L} :

Theorem 3.2. *Let (X, ω) be a translation surface that belongs to the hyperelliptic locus \mathcal{L} . There is a dense set of periodic directions $\theta \in \mathbb{S}^1$ such that, in the direction θ , ω has a metric cylinder containing a Weierstrass point.*

Theorem 3.3. *Let (X, ω) be a translation surface in the hyperelliptic locus \mathcal{L} . Let us assume that the Teichmüller disc of (X, ω) is stabilized by a pseudo-Anosov diffeomorphism and that there exists a completely periodic direction. Then every periodic direction that contains a cylinder invariant by the hyperelliptic involution is completely periodic. Moreover the set of completely periodic directions is dense in \mathbb{S}^1 .*

Remark 3.3.1. Theorem 3.3 immediately implies Theorem 0.2.

The statement of Theorem 3.3 is a weak form of the completely periodicity studied by Calta in genus 2 (see [Cal04]).

Nevertheless, it is not true that the hypothesis of the theorem implies that the surface is completely periodic in the sense of Calta. A direction with a splitting of the surface into two cylinders and two non periodic tori was exhibited on the Arnoux-Yoccoz example see [HLM06]. Similar constructions can be made for surfaces arising from the Thurston-Veech construction.

The following obvious remark shows that the behaviour stated in Theorem 3.3 is indeed special.

Proposition 3.4. *Almost every surface in any stratum does not admit a completely periodic direction.*

Proof. Complete periodicity can be expressed via proportionality of a non-empty set of relative periods. Since any stratum admits a coordinate system given by integration of a basis of relative periods, surfaces with a completely periodic direction are given by a linear subspace of positive codimension in this coordinate system. Since there are only countably many choices of such a basis, the set in question is of Lebesgue measure zero. \square

3.1. Proof of Theorem 3.2.

Definition 3.5. A *slit* is a geodesic segment embedded on a translation surface (in particular, it has no self-intersection and its end points differ). A *slit torus* is a flat torus with a marked point where a slit starting from the marked point is removed.

The key ingredient in the proof is the following lemma.

Lemma 3.6. *Let (X, ω) be a translation surface of area 1 in the hyperelliptic locus \mathcal{L} . Let us assume that the vertical direction is periodic, and, let L be the length of the shortest vertical saddle connection. There is a direction θ with $|\cos(\theta)| \leq 1/L^2$ such that, in the direction θ , the surface (X, ω) has a metric cylinder containing a Weierstrass point.*

Proof. If a vertical cylinder is invariant by the hyperelliptic involution, there is nothing to prove. Otherwise, the vertical direction contains two cylinders C_1 and C_2 exchanged by the involution.

Section 2 describes the completely periodic vertical directions. In fact, it also gives all the types of periodic directions. By rescaling, we may suppose that the integral along the core curve of C_1 (and hence also of C_2) is in $\mathbb{Q} \cdot i$, while the width is in \mathbb{Q} . Hence there is a surface (Y, η) arbitrarily close to (X, ω) with cylinders C_i of the same size as those on X and with relative periods in $\mathbb{Q}[i]$. The surface (Y, η) is square-tiled by construction. Hence its vertical direction is completely periodic. A path between (X, ω) and (Y, η) fixing C_1 and C_2 gives a way of describing (X, ω) as a deformation of a completely periodic surface, which leaves the cylinders C_1 and C_2 unchanged and does not change the topology of the complementary regions.

The periodic configurations with two cylinders exchanged by the hyperelliptic involution are listed in Figure 1.

Using this list, we remark that $X \setminus (C_1 \cup C_2)$ falls into the following list:

- (1) a torus cut along a slit (Figure 1a)
- (2) a periodic cylinder (Figure 1b)
- (3) a union of two tori T_1 and T_2 cut along vertical slits (Figure 1e)
- (4) a union of two periodic cylinders (Figure 1f)
- (5) a slit torus and a periodic cylinder (Figure 1g)

(6) empty (Figure 1h).

All the connected components of $X \setminus (C_1 \cup C_2)$ are invariant under the hyperelliptic involution. Thus the vertical direction contains a periodic cylinder fixed by the involution when $X \setminus (C_1 \cup C_2)$ is a cylinder (case (2)) or a union of a cylinder and a torus (case (5)).

Consequently, we assume that $X \setminus (C_1 \cup C_2)$ is the union of one or two slit tori fixed by the hyperelliptic involution. Let T be one of these tori. We call *the elliptic involution* of a torus T embedded into a flat surface of higher genus X an elliptic involution that fixes one of the singularities of X that lies on T .

Claim 3.7. *Suppose that T is a slit torus and that the direction of the slit does not contain a lattice vector of Λ where $T \cong \mathbb{C}/\Lambda$. Then T contains a metric cylinder that does not intersect the slit and that is invariant under the hyperelliptic involution.*

Proof of the Claim. Up to normalization, the lattice is

$$\Lambda = \left\langle \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} x \\ y \end{pmatrix} \right\rangle$$

and slit is vertical. By our hypothesis, we may assume $x \in (0, 1)$. As shown in Figure 2, the direction $\begin{pmatrix} x \\ y \end{pmatrix}$ is periodic and the cylinder contains a Weierstrass point. Moreover, the periodic leaves of the cylinder do not intersect the slit. \square

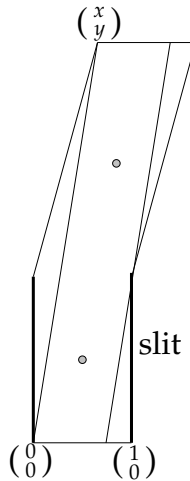


FIGURE 2. A cylinder fixed by the elliptic involution on a slit torus

The lengths of each slit is at least L and the area of T is less than 1. Thus the distance between the left and right boundaries of T is at most $1/L$ and the length of the cylinder is at least L . This yields $|\cos(\theta)| \leq 1/L^2$.

It remains to consider the case described in Figure 1h when $X \setminus (C_1 \cup C_2)$ is empty. There is a segment going from the Weierstrass point which is in the middle of the saddle connection labelled by 3 to the middle of the saddle connection labelled by 5. This segment and its image under the hyperelliptic involution form a closed geodesic γ in a direction θ . The periodic geodesic γ is the core of a cylinder (containing a Weierstrass point) and the angle θ satisfies $|\cos(\theta)| \leq 1/L^2$. This ends the proof of Lemma 3.6. \square

Proof of Theorem 3.2. We assume that the area of (X, ω) is equal to one and we fix $\varepsilon > 0$ and $\phi \in \mathbb{S}^1$. Applying Masur's theorem, there exists a periodic direction ψ with $|\psi - \phi| < \varepsilon/2$. On the other hand, for each δ , there is only finite number of directions with a saddle connection of length less than δ . We may thus assume, without loss of generality, that the length of the shortest saddle connection in the direction ψ is at least $\frac{1}{\sqrt{\sin(\varepsilon/2)}}$. By Lemma 3.6, there is a periodic direction θ with a cylinder containing a Weierstrass point and $|\sin(\theta - \psi)| < \sin(\varepsilon/2)$ for ε small enough. Thus $|\phi - \theta| < \varepsilon$. Theorem 3.2 is proven. \square

3.2. Proof of Theorem 3.3. We first recall some facts concerning the J -invariant of Kenyon-Smillie [KS00] and the SAF-invariant.

Theorem 3.8 (Caltá-Smillie [CS07] Theorem 1.5). *Assume that (X, ω) is stabilized by a pseudo-Anosov diffeomorphism and that there exists a completely periodic direction. Then the SAF-invariant vanishes for all directions of the trace field.*

The following facts concerning the SAF-invariant are essentially contained in Arnoux's thesis [Arn81] and were used by Calta [Cal04] and also by McMullen [Mc2] (who works with the flux instead of the SAF-invariant).

Lemma 3.9. *Let (Y, α) be a translation surface in the stratum $\mathcal{H}(2)$ such that the SAF-invariant vanishes in the vertical direction. Then the vertical direction is completely periodic.*

Lemma 3.10. *Let (Y, α) be a translation surface in the stratum $\mathcal{H}(1, 1)$ such that the SAF-invariant vanishes in the vertical direction. If there are two non homologous vertical saddle connections, then the vertical direction is completely periodic.*

Proof of Lemmas 3.9 and 3.10. For the sake of the completeness, we sketch the proof of the Lemmas 3.9 and 3.10. We recall that, in genus 2, if the SAF-invariant vanishes then the flow in the vertical direction is not minimal [Ar]. Therefore, there is a vertical saddle connection.

If (Y, α) belongs to $\mathcal{H}(2)$, the induced map of the vertical flow on a suitable transversal is an interval exchange transformation on 4 intervals. Since there is a saddle connection, it reduces to an interval exchange transformation on 3 intervals. An interval exchange on 3 intervals with SAF-invariant is equal to 0 is periodic (see [Arn81]). Thus, the vertical flow on (Y, α) is periodic.

If (Y, α) belongs to $\mathcal{H}(1, 1)$, the induced map of the vertical flow on a suitable transversal τ is an interval exchange transformation on 5 intervals. By hypothesis, there are two vertical saddle connections γ_1 and γ_2 such that $Y \setminus (\gamma_1 \cup \gamma_2)$ is connected. Thus, the induced map on τ reduces to an interval exchange transformation on 3 intervals with SAF-invariant equal to 0. This interval exchange transformation is periodic and thus vertical flow is periodic. □

Proof of Theorem 3.3. Let us consider a cylinder C fixed by the hyperelliptic involution on (X, ω) . Let θ be the direction of C . It is a direction of the holonomy field (see background) thus, by Calta-Smillie's result, the SAF-invariant vanishes in the direction θ . Without loss of generality we may assume that the direction θ is the vertical direction. The complement of C is a slit surface Y with vertical boundaries. We have to prove that the vertical flow is completely periodic on Y . The SAF-invariant is equal to 0 on C , thus it vanishes on Y . The topological type of Y can be deduced from the description of the completely periodic directions (see Figure 1) by the same argument as in Lemma 3.6.

There is a canonical way to associate with Y a compact surface \hat{Y} without boundary. Y is obtained from X by removing a cylinder \bar{C} invariant under the hyperelliptic involution. A slit on Y corresponds to a saddle connection on the boundary of C that is not invariant under the hyperelliptic involution. Since C is fixed by the hyperelliptic involution, these slits come in pairs. \hat{Y} is obtained from Y by gluing the pairs of slits exchanged by the hyperelliptic involution. The vertical flow on Y is periodic if and only if it is periodic on \hat{Y} .

Referring to the Figure 1, we denote the cylinders by I, II, III, etc from the left to the right.

- \hat{Y} belongs to $\mathcal{H}(2)$, if II is removed in Figure 1a.
- \hat{Y} belongs to $\mathcal{H}(2)$, if II is removed in Figure 1b.
- \hat{Y} belongs to $\mathcal{H}(1, 1)$, if I is removed in Figure 1c.
- \hat{Y} belongs to $\mathcal{H}(1, 1)$, if II is removed in Figure 1c.
- \hat{Y} belongs to $\mathcal{H}(1, 1)$, if III is removed in Figure 1c.
- \hat{Y} belongs to $\mathcal{H}(2)$, if I is removed in Figure 1d.
- \hat{Y} belongs to $\mathcal{H}(2)$, if II is removed in Figure 1d.
- \hat{Y} is the union of two cylinders, if III is removed in Figure 1d.

- \hat{Y} belongs to $\mathcal{H}(2)$, if II is removed in Figure 1e.
- \hat{Y} belongs to $\mathcal{H}(2)$, if IV is removed in Figure 1e.
- \hat{Y} belongs to $\mathcal{H}(2)$, if II is removed in Figure 1f.
- \hat{Y} belongs to $\mathcal{H}(2)$, if IV is removed in Figure 1f.
- \hat{Y} belongs to $\mathcal{H}(2)$, if IV is removed in Figure 1g.
- \hat{Y} belongs to $\mathcal{H}(2)$, if II is removed in Figure 1g.
- \hat{Y} belongs to $\mathcal{H}(2)$, if I is removed in Figure 1i.
- \hat{Y} is a cylinder, if II is removed in Figure 1i
- \hat{Y} belongs to $\mathcal{H}(1, 1)$ if I is removed in Figure 1j.
- \hat{Y} is a cylinder, if II is removed in Figure 1j
- \hat{Y} belongs to $\mathcal{H}(2)$, if I is removed in Figure 1k.
- \hat{Y} belongs to $\mathcal{H}(2)$, if II is removed in Figure 1k.

By Lemma 3.9, the vertical direction is completely periodic when $\hat{Y} \in \mathcal{H}(2)$. We have to check the hypothesis of Lemma 3.10 when \hat{Y} belongs to $\mathcal{H}(1, 1)$. We treat the case where the cylinder I is removed in Figure 1c. The analysis in the other cases is more or less the same. The surface Y contains two vertical saddle connections isometric to the saddle connections labelled by 1 and 2 in Figure 1c. These connections don't disconnect the surface thus, by Lemma 3.10, the flow in the vertical direction is completely periodic on \hat{Y} . Therefore the vertical direction is completely periodic on (X, ω) .

Combining Theorem 3.2 and the previous argument, we immediately deduce that there is a dense set of completely periodic directions on (X, ω) . The theorem is proven. \square

4. DETECTING THE CLOSURE: REDUCTION STEPS

In this section we show in several instances that a completely periodic direction on a surface (X, ω) plus some irrationality condition implies the existence of a more useful completely periodic direction on a surface (Y, η) in the $\mathrm{GL}_2^+(\mathbb{R})$ -orbit closure of (X, ω) . Moreover, (Y, η) can be chosen such that the new completely periodic direction still satisfies some irrationality condition. The underlying strategy of all lemmas in this section is roughly the same. Finally, we arrive in a situation where we can show that the $\mathrm{GL}_2^+(\mathbb{R})$ -orbit closure of (Y, η) is all of \mathcal{L} .

A bit more precisely, we start with a direction p on (X, ω) for which there exists a splitting of the surface into some cylinders and/or tori. We apply a one parameter unipotent subgroup U (with eigenvector p) on (X, ω) . This action stabilizes globally the splitting and acts on the product of tori and/or cylinders. We then apply Ratner's theorem on orbit closures of the one parameter unipotent subgroup U inside U^k or $\mathrm{SL}_2(\mathbb{R})^k$ for $k = 2, 3$. The orbit closure is of the form $H \cdot (X, \omega)$, where

H is a closed subgroup of $SL_2(\mathbb{R})^k$ for $k = 2, 3$, in the closure of the $SL_2(\mathbb{R})$ -orbit of (X, ω) . Then with “generic” conditions, we get that H is as big as possible. We then choose $(Y, \eta) = h \cdot (X, \omega)$, for h generic.

Two types of splitting directions will be particularly useful. The first one is a *3C-direction*; this is a completely periodic direction with three cylinders and a configuration of saddle connections as the vertical direction of Figure 1d. Of course, this is not the only direction with three cylinders, but we stick to this short notation also used in [HLM06]. The second one is defined as follows.

Definition 4.1. A $2T_{\text{fix}}2C$ -direction is a direction with two simple cylinders exchanged by the hyperelliptic involution and such that the complement decomposes into two tori. The vertical direction in Figure 1e is an example, which is in fact completely periodic. A $2T_{\text{fix}}2C$ -direction is not always completely periodic. In fact if a $2T_{\text{fix}}2C$ -direction is not completely periodic, the flow, in that direction, contains one or two minimal component(s), corresponding to the two tori. We will say that a $2T_{\text{fix}}2C$ -direction is *irrational* if it is not completely periodic.

Remark 4.1.1. We alert a reader who has also read [HLM06], that there such a direction was simply called $2T2C$. In this paper we need to distinguish $2T_{\text{fix}}2C$ -directions from $2T2C_{\text{fix}}$ -directions. A *completely periodic $2T2C_{\text{fix}}$ -direction* (e.g. in Figure 1f) has a two simple cylinders *fixed* by the hyperelliptic involution and, cutting along all saddle connections in that direction, the complement consists also of two components, exchanged by the hyperelliptic involution. These components can be glued in a obvious way to two tori. It will be convenient also to talk of *irrational $2T2C_{\text{fix}}$ -directions*, although this is some abuse of terminology. Such a direction (cf Figure 7a) also has two simple cylinders fixed by the hyperelliptic involution, but no saddle connections in the complement. This complement is then connected and thus it is a surface of genus two with two slits (rather than two tori).

We now give some useful definitions for the upcoming lemmata.

Definition 4.2. For any lattice Λ we denote by Λ' the normalized area one lattice obtained by rescaling Λ by a homothety. We say that two lattices Λ_1 and Λ_2 are *strongly non-commensurable with respect to a direction $p \in \mathbb{R}^2$* , if there is no unipotent element u with eigenvector p such that $u(\Lambda'_1)$ and Λ'_2 (or Λ'_1 and $u(\Lambda'_2)$) are commensurable.

Definition 4.3. We say that 3 moduli m_i of cylinders, in a completely periodic direction are *pairwise incommensurable*, if $m_i/m_j \notin \mathbb{Q}$ for $i \neq j$, i. e. if they are \mathbb{Q} -linearly independent or admit a \mathbb{Q} -linear relation $\sum_{i=1}^3 a_i m_i = 0$ unique up to scalars and with $a_i \neq 0$ for all i .

The first lemma consists of the key argument of [HLM06]. We recall the proof in detail. From Lemma 4.5 to Lemma 4.11 we will relax the hypothesis on the translation surface (X, ω) .

Lemma 4.4. *Let us assume that $(X, \omega) \in \mathcal{L}$ contains a 3C-direction. Then it contains also a transverse $2T_{\text{fix}}2C$ -direction, denoted by p : it is given by the four homologous saddle connection drawn in Figure 3. Let us assume that the direction p has irrational and strongly non-commensurable tori. We also assume that the two lattices uniformizing the two tori do not possess vectors in the direction of p .*

Then the $\text{GL}_2^+(\mathbb{R})$ -orbit closure of (X, ω) is \mathcal{L} .

Proof. Let us denote by Z the closure of (X, ω) under $\text{SL}_2(\mathbb{R})$ inside \mathcal{L}_1 , the real hypersurface of translation surfaces of ω -volume one. One has to show that $Z = \mathcal{L}_1$.

Let U the unipotent subgroup of $\text{SL}_2(\mathbb{R})$ generated by unipotent elements u having p as eigenvector. Then the action of U on (X, ω) is very simple: it stabilizes globally the direction p and it acts on each component of the splitting. Thus U acts on the space of a pair of tori and a cylinder, which is isomorphic to $(\text{SL}_2(\mathbb{R})/\text{SL}_2(\mathbb{Z}))^2 \times U$. Thanks to Ratner's theorem, the closure of $U \cdot (X, \omega)$ is algebraic, i. e. $H \cdot (X, \omega)$ where H is a closed subgroup of $\text{SL}_2(\mathbb{R})^2 \times U$ containing U diagonally embedded.

The hypothesis that the two tori are irrational and strongly non-commensurable implies that this splitting is "generic" for Ratner, i. e. $H = \text{SL}_2(\mathbb{R})^2 \times U$. This Lie group has dimension 7 and since we can use $\text{SL}_2(\mathbb{R})$ to replace the connection vector of the four homologous saddle connections by any vector in \mathbb{R}^2 , we have proved that Z contains a subset of real dimension at least 9. Since $\dim_{\mathbb{R}} \mathcal{L}_1 = 11$ and since the application of Ratner's theorem keeps the ratios of the splitting pieces fixed, the subset we know to be contained in Z consists precisely of the surfaces with given ratios of the splitting pieces. We have to catch the two missing dimensions by varying these ratios.

Let us consider the direction \tilde{p} obtained by applying a simple Dehn twist around the vertical non-simple cylinder of the 3C-direction (see Figure 3). The direction \tilde{p} is obviously again of type $2T_{\text{fix}}2C$. Since the saddle connections of a $2T_{\text{fix}}2C$ -direction are homologous, the splitting in the direction \tilde{p} still exists in a neighborhood of (X, ω) .

We write $(X, \omega) = T_1 \# C_1 \# T_2 \# C_2$ to denote that (X, ω) is obtained as the connected sum of the T_i and C_i glued along a fixed set of slits, which is suppressed in the notation. We know that orbit closure of (X, ω) contains

$$(Y_{(u_1, u_2)}, \eta_{(u_1, u_2)}) = u_1 T_1 \# C_1 \# u_2 T_2 \# C_2$$

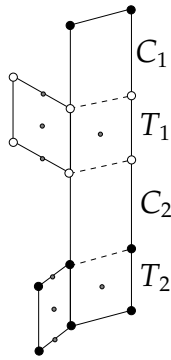


FIGURE 3. A “diagonal” resplitting $2T_{\text{fix}}2C$ -direction on a $3C$ -direction.

for $u_i \in U$. For any pair (u_1, u_2) close enough to zero, the Dehn-twisted unipotent-admissible configuration still exists on $Y_{(u_1, u_2)}$. We denote this decomposition of the modified surface in the new direction by

$$(Y_{(u_1, u_2)}, \eta_{(u_1, u_2)}) = \widetilde{T}_1 \# \widetilde{C}_1 \# \widetilde{T}_2 \# \widetilde{C}_2.$$

If the u_i are chosen such that Dehn-twisted direction \tilde{p} has irrational and strongly non-commensurable tori, too, then we may apply Ratner’s theorem as in the beginning of the proof and again with the conclusion $H = G$.

Two things now need to be checked by direct calculation. First, the set of u_i where the Dehn-twisted direction \tilde{p} is not irrational or not strongly non-commensurable is a countable union of subvarieties of real codimension at least one. Second, the u_i -twisting can indeed be used to adjust the ratios of areas. More precisely, the map

$$\varphi : (u_1, u_2) \mapsto (\text{area}(\widetilde{T}_1(u_1, u_2))/\text{area}(\widetilde{C}_1(u_1, u_2)), \text{area}(\widetilde{T}_2(u_1, u_2))/\text{area}(\widetilde{C}_2(u_1, u_2)))$$

is an invertible function in a neighborhood of $(u_1, u_2) = (0, 0)$. This is checked in [HLM06] Lemma 5.9.

In conclusion, the orbit closure of (X, ω) contains points with all ratios of splitting pieces close to the original ratios and for almost all these ratios (with respect to the Lebesgue measure) we can apply Ratner’s theorem in the new splitting direction. Thus the orbit closure of (X, ω) contains a subset of \mathcal{L} positive measure. Recall that the geodesic flow is ergodic on \mathcal{L} ([Mas82, Vee82]). Therefore Z has full measure in \mathcal{L} . Since Z is closed, this completes the proof. \square

Lemma 4.5. *Let us assume that $(X, \omega) \in \mathcal{L}$ contains an irrational $2T_{\text{fix}}2C$ -direction. In addition we assume that the two tori of the splitting, are strongly non-commensurable. Then the $\text{GL}_2^+(\mathbb{R})$ -orbit closure of (X, ω) is \mathcal{L} .*

Proof. The idea is to apply the previous Lemma 4.4. Let p denote the direction of the $2T_{\text{fix}}2C$ -direction. As usual, let U be the unipotent subgroup of $SL_2(\mathbb{R})$ generated by unipotent elements u having p as eigenvector. By Ratner's theorem, in the $SL_2(\mathbb{R})$ orbit closure of (X, ω) , one finds surfaces $H \cdot (X, \omega)$ where H is a closed unimodular subgroup of $SL_2(\mathbb{R})^2 \times U$. By hypothesis, H contains at least the product $SL_2(\mathbb{R})^2$. Thus one can apply a unipotent matrix in each torus independently, in order to obtain a surface (Y, η) in the $SL_2(\mathbb{R})$ -orbit closure of (X, ω) with a $2T_{\text{fix}}2C$ -direction and an adequate transverse $3C$ -direction (cf. Figure 3).

Of course, by construction, the tori of the $2T_{\text{fix}}2C$ -direction on (Y, η) are still irrational. Applying a diagonal matrix in $SL_2(\mathbb{R})$, we obtain a new surface, (Y, η) , with above properties and in addition with two strongly non-commensurable tori. We can then apply Ratner's theorem as above (see Lemma 4.4). \square

Lemma 4.6. *If $(X, \omega) \in \mathcal{L}$ contains an irrational $2T_{\text{fix}}2C$ -direction, then the $GL_2^+(\mathbb{R})$ -orbit closure of (X, ω) is \mathcal{L} .*

Proof. The strategy is to use the previous Lemma 4.5. We will prove that there exists a surface (Y, η) in the $GL_2^+(\mathbb{R})$ -orbit closure of (X, ω) with an irrational $2T_{\text{fix}}2C$ -direction containing two strongly non-commensurable tori.

By rotating, we can and will assume that the $2T_{\text{fix}}2C$ -direction is vertical as in Figure 4. We apply the unipotent subgroup $\begin{pmatrix} 1 & 0 \\ * & 1 \end{pmatrix}$ to the vertical splitting. Exchang-

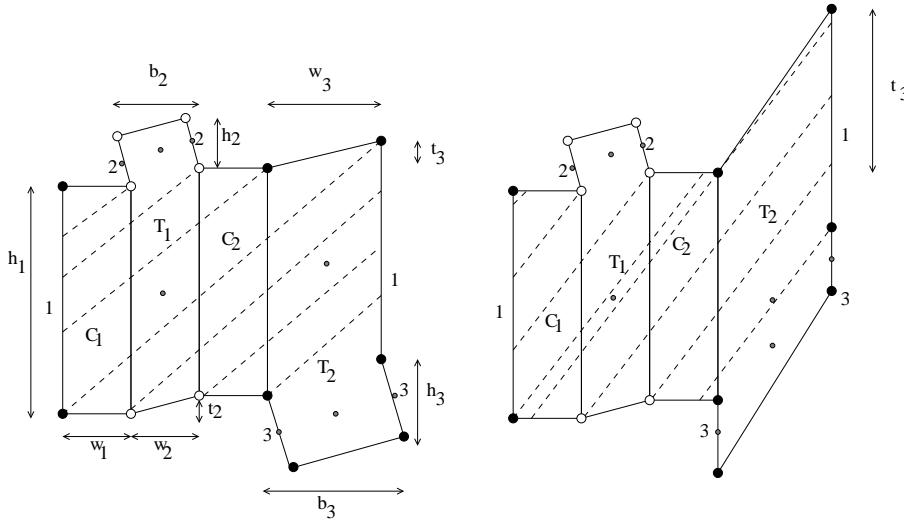


FIGURE 4. A $2T_{\text{fix}}2C$ -direction with an irrational torus and a "diagonal" resplitting with $p > t_3/w_3$ on the left figure and $p < t_3/w_3$ on the right figure

ing the role of T_1 and T_2 if necessary, one can assume that T_1 is irrational. As in Lemma 4.4, we denote the splitting of (X, ω) by $C_1 \# T_1 \# C_2 \# T_2$. As usual, using Ratner's theorem one deduces that the $SL_2(\mathbb{R})$ -orbit closure of (X, ω) contains $C_1 \# SL_2(\mathbb{R}) \cdot T_1 \# C_2 \# T_2$. Said differently, the closure contains all surfaces with the following properties.

First, all the parameters w_1, w_3, h_1, h_3 and b_3 are as given by the original surface (X, ω) . Note that the torus T_2 is not necessarily periodic. If it is, one has $b_3 = w_3$, as indicated in the right figure. Second, the parameters w_2, t_2 and b_2 can be chosen arbitrarily as long as $b_2 > w_2$ and h_2 can be chosen to satisfy the volume condition $(h_1 + h_2) \cdot w_2 = A_1$ where A_1 is the volume of the irrational torus T_1 of (X, ω) . In particular w_2 can be chosen close to 0. By flipping the figure and changing the sign of t_2 , we may suppose that both t_2 and t_3 are non-negative.

Let us denote the splitting in the new direction (indicated by the dotted line) by tildes. This new direction, by construction, crosses k -times the top of each vertical cylinder C_i as indicated on the figure ($k = 0$ in Figure 4 on the left and $k = 1$ on the right). This direction has slope

$$p = \frac{(k+1)h_1 + t_2 + t_3}{2w_1 + w_2 + w_3}.$$

Moreover one can move the parameters w_2, t_2 and b_2 in order to obtain a $2T_{\text{fix}}2C$ -direction for the new splitting in the following way. There are two cases to consider: $p > t_3/w_3$ (see the left figure) and for $p < t_3/w_3$ (see the right figure). The case of equality can be avoided by modifying t_2 slightly. Note that using the hyperelliptic involution it is enough to check the intersection behaviour for the dotted saddle connections emanating from the white singularity on the bottom of C_2 .

Choosing w_2 close to 0 and t_2/w_2 small enough, the line emanating at the white point has the correct intersection behaviour if and only if

$$\frac{kh_1 + t_3}{w_1 + w_3} < p < \frac{(k+1)h_1 + t_3}{w_1 + w_3}.$$

This condition can always be satisfied choosing k suitably and equality can again be excluded by modifying t_2 slightly. Therefore the dotted line provides a new splitting $\widetilde{C}_1 \# \widetilde{T}_1 \# \widetilde{C}_2 \# \widetilde{T}_2$.

Thus, until now, we have found a resplitting in a $2T_{\text{fix}}2C$ -direction for all t_2, w_2 and h_2 in a small open intervals. We will check that for almost all triples (t_2, w_2, b_2) , subject to the condition that $(h_1 + h_2)w_2 = A_1$ is fixed, this splitting satisfies the conditions of Lemma 4.5. Namely, for almost all triples the two new tori \widetilde{T}_1 and \widetilde{T}_2 are irrational and strongly non-commensurable.

We give a detailed proof for the left figure case; the right figure case being completely similar. Thus the lattices of the tori (for the resplitting $2T_{\text{fix}}2C$ -direction) are

$$\widetilde{\Lambda}_1 = \left\langle \widetilde{v}_1 := \begin{pmatrix} w_2 \\ t_2 \end{pmatrix}, \widetilde{w}_1 := \begin{pmatrix} 2w_2 - b_2 + 2w_1 + w_3 \\ (k+1)h_1 + h_2 + t_2 + t_3 \end{pmatrix} \right\rangle$$

and

$$\widetilde{\Lambda}_2 = \left\langle \widetilde{v}_2 := \begin{pmatrix} w_3 \\ t_3 \end{pmatrix}, \widetilde{w}_2 := \begin{pmatrix} 2w_3 - b_3 + 2w_1 + w_2 \\ (k+1)h_1 + h_3 + t_2 + t_3 \end{pmatrix} \right\rangle.$$

One has to make sure that these two lattices do not possess vectors in the direction of p . Moreover we want Λ_1 and Λ_2 to be strongly non-commensurable with respect to p in order to apply previous lemma. A direct calculation shows that if Λ_1 (respectively Λ_2) possesses vectors in the direction of p then there exists $n \in \mathbb{Z}$ such that

$$\frac{nt_2 + h_2}{(k+1)h_1 + h_3} \in \mathbb{Q} \quad \left(\text{respectively } \frac{nt_3 + h_3}{(k+1)h_1 + h_2} \in \mathbb{Q} \right).$$

One gets similar conditions for the strong non-commensurability of the lattices. These two conditions exclude only a countable union of 2-dimensional subvarieties (in the space with coordinates w_2, t_2, h_2 and b_2 subject to $(h_1 + h_2)w_2 = A_1$), hence a set of Lebesgue measure zero. Therefore we have found a resplitting in a $2T_{\text{fix}}2C$ -direction, for almost all t_2, w_2 and h_2 , with two irrational and strongly non-commensurable tori. We then conclude the proof of Lemma 4.6 by using Lemma 4.5. \square

Lemma 4.7. *If (X, ω) has a 3C-direction with incommensurable moduli, the $\text{SL}_2(\mathbb{R})$ orbit closure of (X, ω) is \mathcal{L} .*

Proof. If p denotes the 3C-direction, let U be the subgroup of $\text{SL}_2(\mathbb{R})$ generated by unipotent elements with eigenvector p . We will also denote by \tilde{p} the transversal $2T_{\text{fix}}2C$ -direction (see Figure 3). We use Ratner's theorem for U on the space of triples of normalized lattices $(\text{SL}_2(\mathbb{R})/\text{SL}_2(\mathbb{Z}))^3$ to ensure that the direction \tilde{p} possesses an irrational torus. Then we conclude by using Lemma 4.6. \square

In order to prove similar lemmas for other completely periodic directions, incommensurability is not strong enough. This will be clear from the covering constructions in Section 7. In Section 5 we prove that if (X, ω) is a pseudo-Anosov surface and if the trace field is totally real and has degree 3 over \mathbb{Q} then any non-parabolic completely periodic direction provides 3 moduli of cylinders pairwise incommensurable (see Corollary 5.2). Hence, in the following lemmas, we can replace "pairwise incommensurable moduli" by "non-parabolic" for surfaces arising from the Thurston-Veech construction.

Lemma 4.8. *If (X, ω) has a completely periodic $2T_{\text{fix}}2C$ -direction with pairwise incommensurable moduli, then the $GL_2^+(\mathbb{R})$ -orbit closure of (X, ω) is \mathcal{L} .*

Proof. Using the action of $SL_2(\mathbb{R})$ we may suppose that the $2T_{\text{fix}}2C$ -direction is vertical and that the bottom of the cylinders C_i is horizontal. Suppose that the saddle connections of slope $p := (h_1 + t_2 + t_3)/(2w_1 + w_2 + w_3)$ intersect the vertical saddle connections as drawn in Figure 5. Then the direction of slope p is again

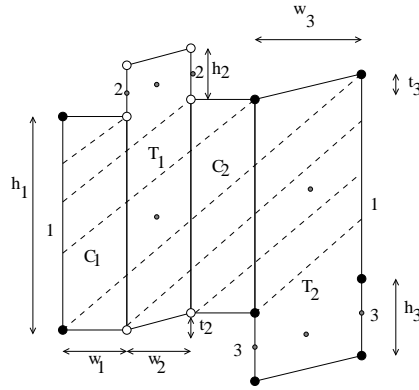


FIGURE 5. Resplitting of a $2T_{\text{fix}}2C$ -direction

$2T_{\text{fix}}2C$ and we want to make sure that, say, the torus containing the top of T_2 is not periodic. Sliding the Weierstrass points along the slope p we observe that this unwanted property holds if

$$\frac{h_2 + h_1}{2p} - \frac{2w_1 + w_2 + w_3}{2} \in \mathbb{Q}w_3.$$

Equivalently, we have to ensure that $t_3 + t_2$ does not lie in a coset of \mathbb{Q} in \mathbb{R} i.e. $t_3 + t_2 \notin \mathbb{Q}x$ for any $x \in \mathbb{R}$. By hypothesis the orbit closure of (X, ω) under the vertical unipotents contains a one-parameter subgroup that fixes C_1 and hence C_2 . Let $m_1 = w_1/(h_1 + h_2)$ and $m_2 = w_2/(h_1 + h_3)$ be the modulus of T_1 and T_2 respectively. Simple cylinders persist under small deformations. For $u \in \mathbb{R}$ small enough, we may thus replace t_1 by $t_1 + u$ and t_2 by $t_2 + um_2/m_1$ to obtain a surface in the unipotent orbit closure of (X, ω) still with a $2T_{\text{fix}}2C$ -direction. Since m_2/m_1 is irrational by pairwise incommensurability, we can choose u in order to avoid the unwanted coset. We can now apply Lemma 4.6.

It remains to check that one can always choose t_2 and t_3 with the desired intersection property. This property is surely satisfied when both t_2 and t_3 are close to zero. Recall that a twist t_2 (resp. t_3) is only well-defined up to integer multiples

$h_1 + h_2$ (resp. $h_1 + h_3$). It suffices to find the resplitting not on (X, ω) but on a surface in the orbit closure of vertical unipotents. Hence it suffices to find $u \in \mathbb{R}$ such that

$$uw_2 + t_2 \pmod{h_1 + h_2} \quad \text{and} \quad uw_3 + t_3 \pmod{h_1 + h_3}$$

are both close to zero. Such u exist, since m_1/m_2 is irrational by pairwise incommensurability. \square

Lemma 4.9. *If (X, ω) has a completely periodic $2T2C_{\text{fix}}$ -direction (as in Figure 1f or Figure 6 (a) below) and such that the moduli m_i of the cylinders $\{C_1, C_2, T_1\}$ are pairwise incommensurable, then the $GL_2^+(\mathbb{R})$ -orbit closure of (X, ω) is \mathcal{L} .*

Proof. We distinguish two cases. Suppose the $2T2C_{\text{fix}}$ -direction is vertical as in Figure 6 (a). We first treat the case $h_2 = h_3$ as suggested by the figure. This is quite

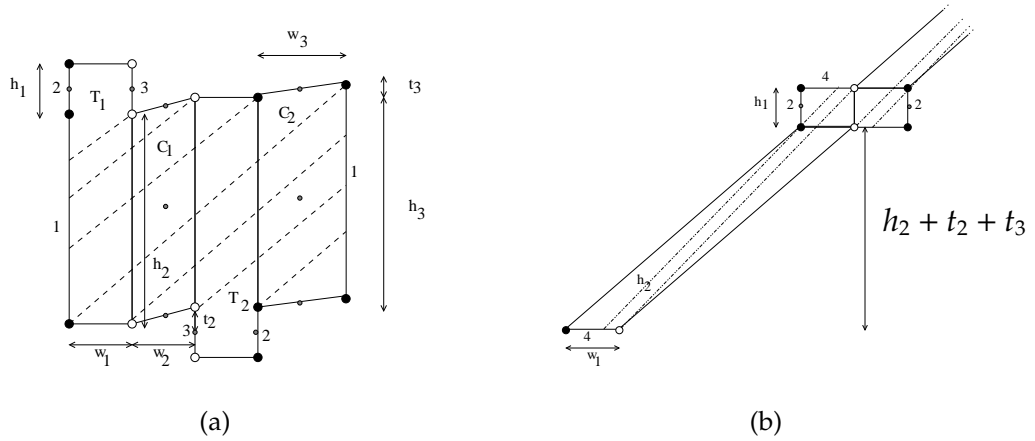


FIGURE 6. Resplitting of a $2T2C_{\text{fix}}$ -direction with $h_2 = h_3$

analogous to the case of a $2T2C_{\text{fix}}$ -direction: Using pairwise incommensurability we may suppose that t_2 and t_3 are both close to zero and chosen such that the indicated splitting exists. Instead of resplitting in the direction of a 'simple Dehn twist around the almost-cylinder of height h_2 ' we may also use a k -fold Dehn twist, for t_2 and t_3 even closer (depending on k) to zero. All these resplitting directions are irrational $2T2C_{\text{fix}}$ -directions and the complement of the two cylinders looks as in Figure 6 (b). The dotted lines have slope

$$\tilde{p} = \frac{h_2 + t_2 + t_3}{k(2w_1 + w_2 + w_3) - w_1}.$$

If for some m

$$\frac{h_1}{2mw_1} > \tilde{p} > \frac{h_1}{(2m+1)w_1},$$

the direction of the dotted lines have 4 homologous saddle connections. Consequently \tilde{p} is a $2T_{\text{fix}}2C$ -direction, as illustrated in Figure 7 (a).

If we let $w := 2w_1 + w_2 + w_3$, the above condition for \tilde{p} may be rephrased as

$$\frac{k}{2m} \frac{wh_1}{w_1} > h_2 + t_2 + t_3 + \frac{h_1}{2mw_1} \quad \text{and} \quad h_2 + t_2 + t_3 + \frac{h_1}{(2m+1)w_1} > \frac{k}{2m+1} \frac{wh_1}{w_1}.$$

If we choose $k/2m$ close to h_2w_1/wh_1 and m large enough, the inequalities are satisfied for t_2 and t_3 small enough. Moreover the existence of the k -fold Dehn twist for the chosen k gives two bounds for the size of t_2 and t_3 . In addition, if we choose t_2 and t_3 sufficiently irrational, the direction \tilde{p} is an irrational $2T_{\text{fix}}2C$ -direction. Now Lemma 4.6 applies.

We now treat the case that $h_2 \neq h_3$, say $h_2 > h_3$. Consider the resplitting of Figure 7. This is a $2T_{\text{fix}}2C$ -direction p . Using incommensurability and the unipotent

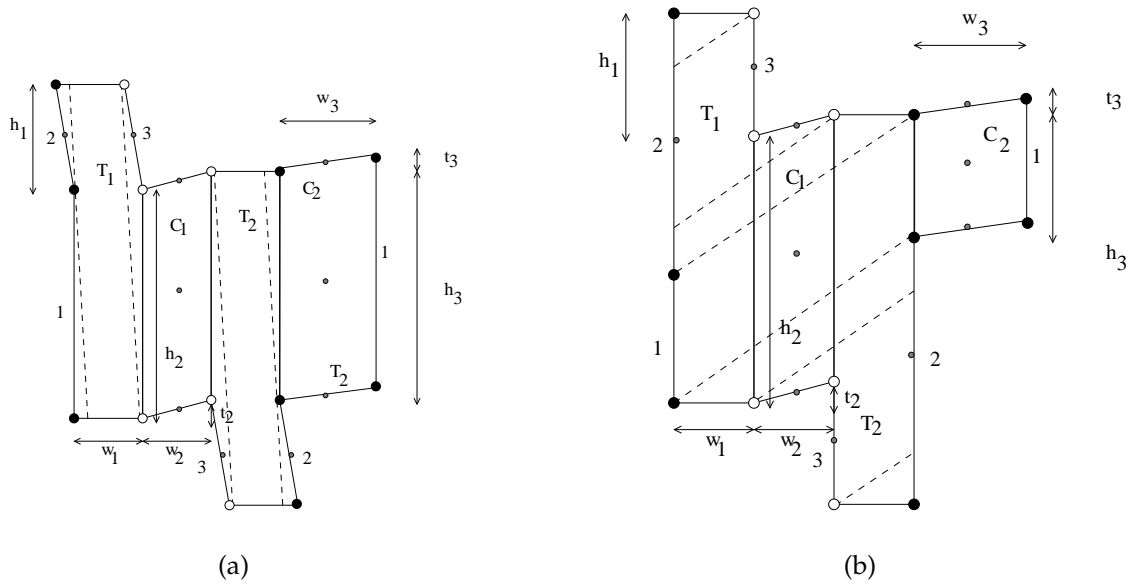


FIGURE 7. (a) $2T_{\text{fix}}2C$ -direction on an irrational $2T2C_{\text{fix}}$ -direction and (b) resplitting of a $2T2C_{\text{fix}}$ -direction with $h_2 \neq h_3$.

action in the vertical direction we may pass to an element in the unipotent orbit closure of (X, ω) and adjust t_2 to any suitable value, preserving the bottom of T_1

horizontal. The parameter t_3 will change, too, but this doesn't matter. We can find t_2 such that the torus in the direction p whose intersection with C_2 is empty, is irrational. Lemma 4.6 applies. \square

Lemma 4.10. *If (X, ω) has a completely periodic direction, as in Figure 1g or Figure 8 below, such that the moduli m_i of the cylinders $\{C_1, C_2, C_3\}$ are pairwise incommensurable then the $GL_2^+(\mathbb{R})$ -orbit closure of (X, ω) is \mathcal{L} .*

Proof. We may suppose that the completely periodic direction is vertical. The unipotent orbit closure of (X, ω) contains all surfaces as in Figure 8, where the bottom of C_1 is horizontal and t_2 can be chosen arbitrarily. The resplitting given

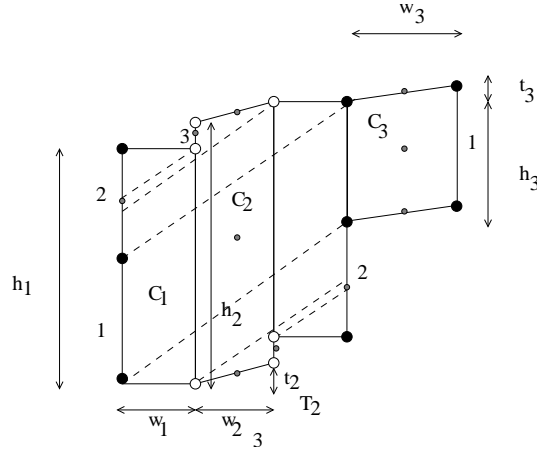


FIGURE 8. Resplitting of a direction with 4 cylinders only one of which is simple

by the dotted lines is a $2T_{\text{fix}}2C$ -direction p . For a suitable choice of t_2 , the torus in the direction p that does not intersect C_3 is irrational. We can now apply Lemma 4.6. \square

Lemma 4.11. *If (X, ω) has a completely periodic direction, as in Figure 1c or Figure 9 below, and such that the moduli m_i of the three cylinders are pairwise incommensurable, then the $GL_2^+(\mathbb{R})$ -orbit closure (X, ω) is \mathcal{L} .*

Proof. Suppose the periodic direction is vertical as in Figure 9. Using a vertical unipotent, we may suppose that C_1 is untwisted, i.e. has a horizontal saddle connection. For t_2 and t_3 sufficiently small but non-zero, the resplitting by dotted lines in Figure 9 is a $2T_{\text{fix}}2C$ -direction p . Moreover, for $t_2 + t_3$ outside a coset of \mathbb{Q} in \mathbb{R} the direction p has an irrational torus. We can arrange that both conditions

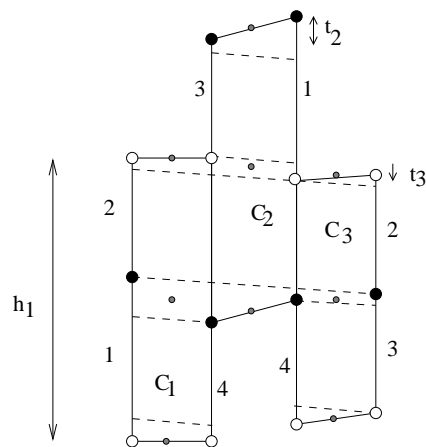


FIGURE 9. Resplitting of a direction with 3 fixed cylinders

hold for a surface in the vertical unipotent orbit closure of (X, ω) , by the same two arguments as in Lemma 4.8. \square

5. SURFACES ARISING FROM THE THURSTON-VEECH CONSTRUCTION

In the whole section (X, ω) will be a surface with two transversal parabolic directions belonging to the hyperelliptic locus \mathcal{L} . We prove that if (X, ω) is not a Veech surface for the most obvious reason and if the pseudo-Anosov diffeomorphism is of a type that can only arise for $g \geq 3$, then its $\mathrm{GL}_2^+(\mathbb{R})$ orbit closure is large.

Theorem 5.1. *Let $(X, \omega) \in \mathcal{L}$ be a surface given by the Thurston-Veech construction with trace field of degree 3. By Theorem 3.3 this surface has infinitely many completely periodic directions. Suppose that one of them is not parabolic. Then*

$$\overline{\mathrm{GL}_2^+(\mathbb{R}) \cdot (X, \omega)} = \mathcal{L}.$$

We first study the properties of the moduli of cylinders for a non parabolic completely periodic direction. We then prove the theorem at the end of this section.

5.1. Commensurability. Let (X, ω) be surface given by the Thurston-Veech construction. We recall that the affine group $\mathrm{SL}(X, \omega)$ of (X, ω) contains a pseudo-Anosov diffeomorphism φ with trace field K and a parabolic element ρ . Thanks to [HLa06] the field K of (X, ω) is totally real. Let us assume that $[K : \mathbb{Q}] = 3$. Let $\sigma_i : K \rightarrow \mathbb{R}$ be the different real embeddings. We fix one of them once and for all

and for given $c \in K$ we write $c' := \sigma_2(c)$ and $c'' := \sigma_3(c)$. Choose $\tau_1, \tau_2 \in \text{Gal}(\mathbb{R}/\mathbb{Q})$ such that

$$\tau_1 \circ \sigma_1 = \sigma_2 \quad \text{and} \quad \tau_2 \circ \sigma_1 = \sigma_3$$

and such that τ_1 have order 3 when restricted to a Galois closure of K/\mathbb{Q} .

Suppose that the horizontal direction of (X, ω) is completely periodic with cylinders of height h_i , circumference c_i and moduli $m_i := h_i/c_i$.

Lemma 5.2. *Suppose the horizontal direction has $s = 3$ cylinders, or that it has $s = 4$ cylinders such that two of them, say the third and the fourth, are interchanged by the hyperelliptic involution. Then either*

- i) *the direction is parabolic, i.e. $m_i/m_j \in \mathbb{Q}$ for all (i, j) , or*
- ii) *the moduli are \mathbb{Q} -linearly independent, or*
- iii) *the moduli are related by*

$$\sum_{i=1}^3 a_i m_i = 0, \quad \text{where } a_i \in \mathbb{Q}^*,$$

i.e. the moduli are not \mathbb{Q} -linearly independent but $m_i/m_j \notin \mathbb{Q}$ for $i \neq j$. In the terminology introduced in the previous section, the direction is either parabolic or pairwise incommensurable.

Proof. Applying an upper triangular unipotent to (X, ω) we may suppose that the relative periods are in $K(i)$. Let $t := \text{tr} \varphi$ and let

$$\psi := \varphi^* + (\varphi^*)^{-1} \in \text{End}(H^1(X, \mathbb{R})).$$

By the hypothesis on the trace field we have a decomposition into eigenspaces of ψ

$$H^1(X, \mathbb{R}) = S \oplus S' \oplus S''$$

where we number the eigenspaces such that $S = \langle \text{Re}(\omega), \text{Im}(\omega) \rangle$ and $\tau_1(S) = S'$, $\tau_2(S) = S''$. Since ψ is symplectic (see [Mc1] Theorem 7.1 and [Mc2] Theorem 9.7), the eigenspaces are orthogonal with respect to the cup product. The surface (X, ω) is covered by the cylinders and we conclude

$$(1) \quad \sum_{i=1}^s m_i c_i c'_i = \sum_{i=1}^s h_i c'_i = \int_X \text{Re}(\omega) \wedge \text{Im} \tau_1(\omega) = \frac{i}{4\pi} \int_X (\omega + \bar{\omega}) \wedge (\tau_1(\omega) - \overline{\tau_1(\omega)}) = 0.$$

Replacing τ_1 by τ_2 we similarly have

$$(2) \quad \sum_{i=1}^s m_i c_i c''_i = 0.$$

Moduli and circumferences of the cylinders exchanged by the hyperelliptic involution are the same. We apply τ_2 to this equation and subtract it from the first one to obtain

$$\sum_{i=1}^3 (m_i - \tau_2(m_i)) \delta_i c_i c_i'' = 0,$$

where $\delta_i = 1$, except for the case of 4 cylinders where $\delta_3 = 2$. Suppose that the lemma is wrong, i. e. there is a relation $a_1 m_1 + a_2 m_2 = 0$. Applying a matrix in $SL_2(K)$ to (X, ω) , we may suppose that m_3 is rational without changing the ratios of the m_i . We deduce from the above equations $m_i = \tau_2(m_i)$ for $i = 1, 2$. Hence in fact all $m_i \in \mathbb{Q}$ and we are in case i). \square

5.2. Completely periodic but not parabolic directions.

Lemma 5.3. *Let $(X, \omega) \in \mathcal{L}$ be a surface given by the Thurston-Veech construction with a completely periodic direction with two cylinders (or with three cylinders, two of which are interchanged by the hyperelliptic involution). Then the direction is parabolic.*

Proof. We discuss the case of two cylinders, the other case is similar since the exchanged cylinders have the same heights and widths. The equations (1) and (2) with $s = 2$ hold in this situation, too. They yield

$$\frac{m_1}{m_2} = -\frac{c_2 c_2''}{c_1 c_1''} = -\frac{c_2 c_2'}{c_1 c_1'}.$$

In particular $\tau_1(m_1/m_2) = m_1/m_2$. Therefore $m_1/m_2 \in \mathbb{Q}$ and the horizontal direction is a parabolic direction with 2 cylinders. The lemma is proven. \square

In particular, we have:

Corollary 5.4. *Let $(X, \omega) \in \mathcal{L}$ be a surface given by the Thurston-Veech construction with $[K : \mathbb{Q}] = 3$. The configuration of every completely periodic non-parabolic direction is one of the configuration drawn in Figure 1c, . . . , Figure 1e or Figure 1g.*

5.3. Proof of Theorem 5.1. By Lemma 5.3 the completely periodic direction has at least 3 orbits of cylinders under the hyperelliptic involution. By Theorem 2.1 and Corollary 5.4, it is thus one of the directions in Figure 1c or 1d, Figure 1e or 1f, or Figure 1g. The Lemmas 4.11, 4.7, 4.8, 4.9 and 4.10, respectively, show that, if the direction is not parabolic, the orbit closure is as big as claimed. The hypothesis on pairwise incommensurability is met because of Lemma 5.2.

6. EXAMPLES

In this section we show that Theorem 5.1 applies to infinitely many surfaces.

Theorem 6.1. *There exist infinitely many surfaces given by the Thurston-Veech construction, with trace field of degree 3, and with a non-parabolic periodic direction.*

We first construct such surfaces (Lemma 6.3), and we then prove that they possess a completely periodic $2T_{\text{fix}}2C$ -direction which is not parabolic (Proposition 6.5).

Proposition 6.2. *Let n be any positive integer and let $P = P_n$ be the polynomial $X^3 - 2(n^2 + 3)X^2 + (7n^2 + 4)X - 4n^2$. Then P possesses only real roots. If $\alpha = \alpha_n$ is the largest root, then $\alpha > 1$.*

Let us define the vectors $V = (V_1, V_2, V_3)$ and $H = (H_1, H_2, H_3)$ by

$$\begin{cases} V_1 = \alpha - 1 \\ V_2 = \frac{1}{n^2}(\alpha^2 - \alpha(6 + n^2) + 4 + n^2) \\ V_3 = 1 \end{cases} \quad \text{and} \quad \begin{cases} H_1 = 2V_1 \\ H_2 = n(V_1 + V_2) \\ H_3 = V_1 + V_3 \end{cases}$$

then V and H are positive, namely $V_i > 0$ and $H_i > 0$ for $i = 1, 2, 3$.

Proof. If A is the symmetric matrix defined by $A = \begin{pmatrix} 5+n^2 & n^2 & 1 \\ n^2 & n^2 & 0 \\ 1 & 0 & 1 \end{pmatrix}$, then the characteristic polynomial χ_A is P . This ensures that P has only real roots. In addition A is an irreducible matrix, indeed $(A^2)_{ij} > 0$ for all i, j . This proves that α is the Perron–Frobenius eigenvalue of the entire matrix A and therefore $\alpha > 1$. Let us show that V is an eigenvector for the eigenvalue value α of the matrix A . The Perron–Frobenius theorem will then show the positivity of V .

For that we have to show that V is a solution of the linear system

$$(3) \quad \begin{cases} (5 + n^2)V_1 + n^2V_2 + V_3 = \alpha V_1 & (L_1) \\ n^2V_1 + n^2V_2 = \alpha V_2 & (L_2) \\ V_1 + V_3 = \alpha V_3 & (L_3) \end{cases}$$

This is a simple verification which makes use of the fact that $\alpha^3 = 2(n^2 + 3)\alpha^2 - (7n^2 + 4)\alpha + 4n^2$. The positivity of H is then clear. \square

Thanks to the previous statement, for any $n \geq 1$, let (X_n, ω_n) be the surface presented in Figure 10.

Lemma 6.3. *The surface (X_n, ω_n) arises from the Thurston-Veech construction. Moreover its trace field is $\mathbb{Q}(\alpha_n)$ and its trace field has degree 3 over \mathbb{Q} if $n > 2$.*

Proof. According to Figure 10 the horizontal horizontal direction of the surface is a completely periodic $3C$ -direction. Let us calculate the moduli of these cylinders and show that they are equal. Using (L_1) and (L_2) in the system (3), one checks that the moduli are

$$\frac{H_3}{V_3} = V_1 + V_3 = \alpha, \quad \frac{H_3 + 2H_1 + nH_2}{V_1} = \alpha, \quad \text{and} \quad \frac{nH_2}{V_2} = n^2 \frac{V_1 + V_2}{V_2} = \alpha.$$

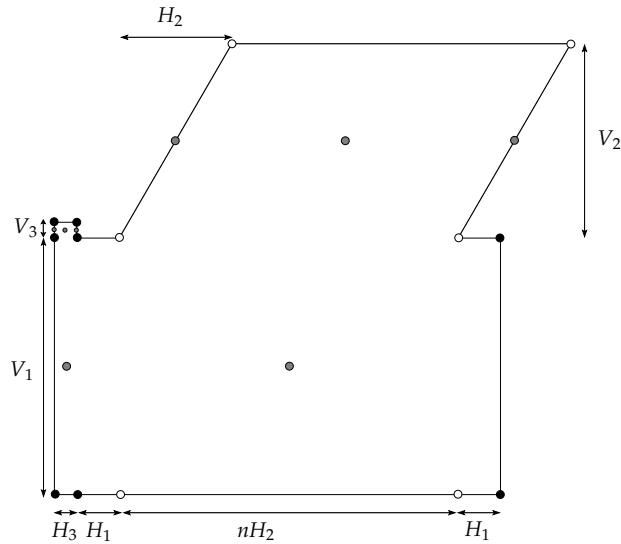


FIGURE 10. The surfaces (X_n, ω_n) in the hyperelliptic locus \mathcal{L} . The vertical direction has been stretched.

All the moduli are equal, thus (X_n, ω_n) is stabilized by the parabolic element $T_\alpha = \begin{pmatrix} 1 & \alpha \\ 0 & 1 \end{pmatrix}$.

Now let us consider the vertical direction; this is a completely periodic $2T_{\text{fix}}2C$ -direction. The two simple cylinders have moduli $V_1/H_1 = 1/2$. The two others cylinders have moduli $(V_1 + V_3)/H_3 = 1$ and $n(V_1 + V_2)(H_2) = 1$. Thus the parabolic element $U_{1/2} = \begin{pmatrix} 1 & 0 \\ \frac{1}{2} & 1 \end{pmatrix}$ stabilises (X_n, ω_n) .

Since (X_n, ω_n) has two transverse parabolic directions, it arises from the Thurston-Veech construction. Moreover (X_n, ω_n) is stabilised by the hyperbolic element TU which has the trace $\frac{1}{2}(4 + \alpha)$. The trace field of (X_n, ω_n) is then $\mathbb{Q}(\alpha_n)$. The next lemma shows that P_n is irreducible over \mathbb{Q} if $n \geq 3$, which will conclude the proof. \square

Lemma 6.4. *Let n be a positive integer. The polynomial $P_n(X) = X^3 - 2(n^2 + 3)X^2 + (7n^2 + 4)X - 4n^2$ is irreducible over \mathbb{Q} if $n > 2$.*

Proof. Since P_n is monic, it is irreducible over \mathbb{Q} if and only if it is irreducible over \mathbb{Z} . As it is of degree 3, it is irreducible over \mathbb{Z} if and only if it has no root in \mathbb{Z} . We check the following equalities:

$$\left\{ \begin{array}{l} P_n(0) = -4n^2 \\ P_n(1) = -1 + n^2 \\ P_n(2) = -8 + 2n^2 \\ P_n(3) = -n^2 - 15 \\ P_n(2n^2 + 2) = -8 - 14n^2 - 2n^4 \\ P_n(2n^2 + 3) = -15 - 11n^2 + 2n^4, \end{array} \right. \quad \text{thus for } n \geq 2 \quad \left\{ \begin{array}{l} P_n(0) < 0 \\ P_n(1) > 0 \\ P_n(2) > 0 \\ P_n(3) < 0 \\ P_n(2n^2 + 2) < 0 \\ P_n(2n^2 + 3) > 0. \end{array} \right.$$

By the intermediate value theorem, if $n > 2$, P_n has 3 real roots α, β, γ satisfying:

$$(4) \quad \left\{ \begin{array}{l} 0 < \gamma < 1 \\ 2 < \beta < 3 \\ 2n^2 + 2 < \alpha < 2n^2 + 3 \end{array} \right.$$

Consequently, P_n has no root in \mathbb{Z} thus it is irreducible over \mathbb{Z} . \square

Remark 6.4.1. The polynomials P_1 and P_2 are not irreducible; indeed, if $n = 1, 2$ we have $P_1 = (X - 1)(X^2 - 7X + 4)$ and $P_2 = (X - 2)(X^2 - 12X + 8)$. More precisely, (X_1, ω_1) is an unramified cover of a Veech surface belonging to $\mathcal{H}(2)$.

6.1. Another completely periodic (non-parabolic) direction on (X_n, ω_n) .

Proposition 6.5. *Let Θ be the slope $V_2/H_2 = n/\alpha$. Then the direction Θ on (X_n, ω_n) is a completely periodic $2T_{\text{fix}}2C$ -direction on (X_n, ω_n) . Moreover, if $n > 1$, this direction is not parabolic.*

We decompose the proof into three steps. We first prove that the direction Θ is completely periodic. We then compute the moduli of the cylinders and finally we prove that one ratio is not rational.

Lemma 6.6. *The direction Θ is a completely periodic $2T_{\text{fix}}2C$ -direction.*

Proof. By definition, γ_5 is closed and the corresponding holonomy vector is

$$\int_{\gamma_5} \omega_n = \begin{pmatrix} H_2 \\ V_2 \end{pmatrix}.$$

Let us prove that γ_4 is also closed. Let x_i be the x -coordinates of intersection point of γ_4 with the top (and bottom) of the horizontal cylinder of height V_1 as illustrated in Figure 12. We will show that $x_i < H_1 + H_3 + nH_2$ for all $i = 1, \dots, n-1$ and $x_n = 3H_1 + 2H_3 + nH_2$ which will ensure that γ_4 is closed.

Elementary geometry gives $\frac{V_1}{x_i - x_{i-1}} = \Theta = \frac{n}{\alpha}$, which yields

$$(5) \quad x_i = \frac{\alpha V_1}{n} + x_{i-1} = \frac{i \cdot \alpha V_1}{n} + x_0 = \frac{i \cdot \alpha V_1}{n} + H_1 + H_3.$$

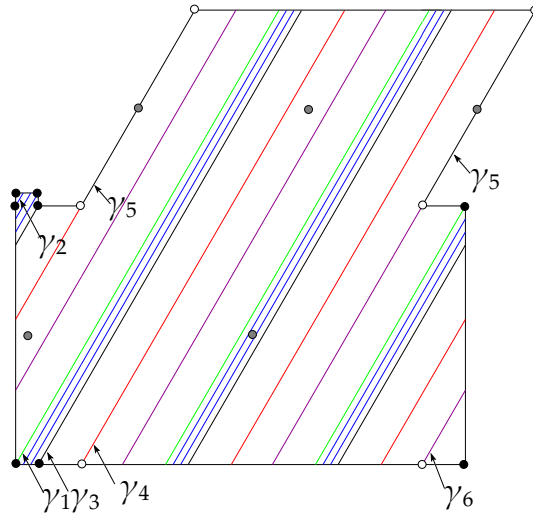


FIGURE 11. Another completely periodic (non-parabolic) $2T_{\text{fix}}2C$ -direction on (X_n, ω_n) .

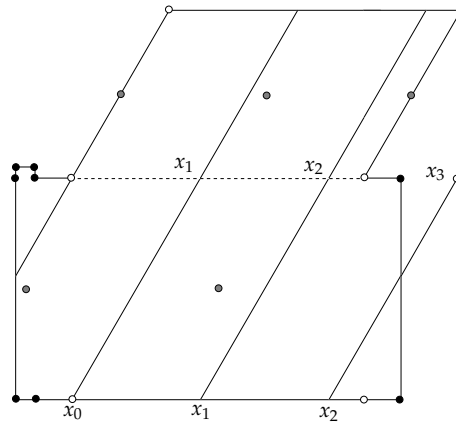


FIGURE 12. The saddle connection γ_4 on (X_3, ω_3) in the direction Θ .

Let $\Delta_i = x_i - (H_1 + H_3 + nH_2)$. Recall that $nH_2 = \alpha V_2$ and $V_1 = \left(\frac{\alpha}{n^2} - 1\right) V_2$ (thanks to (L_2) in Equation (3)). Then

$$\Delta_i = \frac{i \cdot \alpha V_1}{n} - \alpha V_2 = \frac{\alpha V_2}{n} \left(i \left(\frac{\alpha}{n^2} - 1 \right) - n \right).$$

Claim 6.7. *One has*

$$\frac{\alpha}{n^2} - 1 < \frac{n}{n-1}$$

Proof of the Claim. If $n > 2$, we already proved that $\alpha < 2n^2 + 3$ (see Equation (4)).

Hence the claim follows, once we have shown $\frac{2n^2 + 3}{n^2} - 1 = 1 + \frac{3}{n^2} < \frac{n}{n-1}$. This is obvious if $n > 2$. The case $n = 2$ is checked directly. \square

Therefore, if $i \leq n - 1$ we have

$$\Delta_i < \frac{\alpha V_2}{n} \left((n-1) \cdot \frac{n}{n-1} - n \right) = 0.$$

To complete the proof, one has to show that $x_n = 3H_1 + 2H_3 + nH_2$. Equation (5) with $i = n$ gives $x_n = \alpha V_1 + H_1 + H_3$. Therefore

$$\begin{aligned} x_n - (3H_1 + 2H_3 + nH_2) &= \alpha V_1 - 4V_1 - V_1 - V_3 - n^2(V_1 + V_2) = \\ &= (5 + n^2)V_1 + n^2V_2 + V_3 - \alpha V_1 = 0 \quad \text{by } (L_1). \end{aligned}$$

Hence $x_n = 3H_1 + 2H_3 + nH_2$ and γ_4 is closed. In addition, we get the holonomy vector associated to γ_4 :

$$\int_{\gamma_4} \omega_n = \left((n-1)(V_1 + V_2) + V_1 \right)^*.$$

The same calculation shows that γ_1, γ_3 and γ_6 are also closed. It is not difficult that the complement of these four saddle connections consists of two tori. Hence the surface (X_n, ω_n) is decomposed into a $2T_{fix}2C$ -direction in the direction Θ (see Figure 13). One checks that the torus T_1 is actually periodic. By Theorem 3.8 the SAF-invariant vanishes in this direction and the SAF-invariant is equal to zero on cylinders C and torus T_1 . Therefore the SAF-invariant is also equal to zero on T_2 and finally Θ is completely periodic. The lemma is proven. \square

Lemma 6.8. *If C, T_1, T_2 denotes the cylinder decomposition in the direction Θ , then the ratio of the moduli of C and T_1 is*

$$r_1 = \frac{m(C)}{m(T_1)} = \frac{(\alpha - n)(2n^3 - n^2 - (n-1)\alpha)}{2n(\alpha - n^2)}.$$

Proof. According to Figure 13, we can compute the circumference and the height of the cylinders C and T_1 . The circumference of C is just $|\gamma_4|$ where

$$|\gamma_4|^2 = ((n-1)(V_1 + V_2) + V_1)^2 \left(1 + \frac{1}{\Theta^2} \right),$$

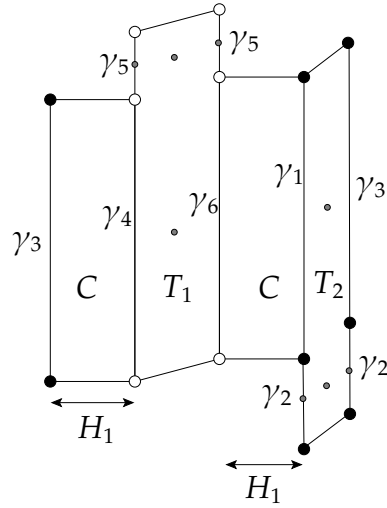


FIGURE 13. The decomposition of (X_n, ω_n) in the direction Θ : this is a completely periodic $2T_{fix}2C$ -direction.

and the height is H_1 .

The circumference of T_1 is just $|\gamma_4| + |\gamma_5|$ where

$$|\gamma_5|^2 = V_2^2 \left(1 + \frac{1}{\Theta^2}\right),$$

and the height is $h(T_1) = (H_1 + H_3 + nH_2) - x_{n-1}$ (see Figure 11). This can be simplified to

$$h(T_1) = nH_2 - \frac{(n-1)\alpha V_1}{n} = \alpha V_2 - \frac{(n-1)\alpha}{n} \left(\frac{\alpha}{n^2} - 1\right) V_2 = \frac{\alpha V_2}{n^3} (2n^3 - n^2 - (n-1)\alpha).$$

Taking the ratio we get:

$$r_1 = \frac{\frac{|\gamma_4|}{H_1}}{\frac{|\gamma_4| + |\gamma_5|}{h(T_1)}} = \frac{|\gamma_4|}{|\gamma_4| + |\gamma_5|} \cdot \frac{h(T_1)}{H_1}.$$

The quantities on the right hand side can be simplified to

$$\frac{|\gamma_4|}{|\gamma_4| + |\gamma_5|} = \frac{(n-1)(V_1 + V_2) + V_1}{(n-1)(V_1 + V_2) + V_1 + V_2} = \frac{\frac{1}{n}\alpha V_2 - V_2}{\frac{1}{n}\alpha V_2} = \frac{\alpha - n}{\alpha}$$

and

$$\frac{h(T_1)}{H_1} = \frac{\frac{1}{n^3}\alpha V_2 (2n^3 - n^2 - (n-1)\alpha)}{2V_1} = \frac{\alpha (2n^3 - n^2 - (n-1)\alpha)}{2n(\alpha - n^2)}.$$

Plugging this into the previous equation, this gives

$$(6) \quad r_1 = \frac{(\alpha - n)(2n^3 - n^2 - (n-1)\alpha)}{2n(\alpha - n^2)}$$

which is the desired equality. □

Lemma 6.9. *The following are equivalent:*

- (1) $r_1 \in \mathbb{Q}$.
- (2) $r_1 = \frac{1}{2}$.
- (3) $n = 1$.

Proof. If $r_1 \in \mathbb{Q}$, using equation (6), we get in the basis $\{1, \alpha, \alpha^2\}$:

$$\begin{cases} n^3(2n - 1 - 2r_1) & = 0 \\ n(2n^2 - 1 - 2r_1) & = 0 \\ n - 1 & = 0 \end{cases}$$

The solution gives $r_1 = \frac{1}{2}$ and $n = 1$. The lemma is proven. □

7. SURFACES WITH A $2T_{\text{fix}}2C$ -DIRECTION AND COVERING CONSTRUCTIONS

The locus $\mathcal{D} \subset \mathcal{L}$ of translation surfaces having a completely periodic direction of type $2T_{\text{fix}}2C$ has proven to be useful above. Unlike the situation in genus two, where pairs of saddle connections exchanged by the hyperelliptic involution *always* exist ([Mc3]), \mathcal{D} is not equal to \mathcal{L} .

In order to show this, we consider coverings $\pi : X \rightarrow Y$ of a flat surface (Y, η) in $\mathcal{H}(2)$. Such a covering is unramified and has degree two. Given Y , the covering π is determined by the choice of $\zeta \in H^1(Y, \mathbb{Z}/2)$ or of a line bundle \mathcal{M} with $\mathcal{M}^2 = \mathcal{O}_Y$. Recall (e.g. [KZ03]) that on Y we have a natural spin structure (i.e. a square root of the canonical bundle) given by $\mathcal{O}_Y(P)$, if $Z(\eta) = 2P$. Since P is a Weierstrass point, this spin structure has odd parity. $\mathcal{O}_Y(P) \otimes \mathcal{M}$ defines another spin structure on Y . By [Ati71], the space C of coverings π has two components, distinguished by the parity of this spin structure $h^0(Y, \mathcal{O}_Y(P) \otimes \mathcal{M}) \pmod{2}$. Let $Z(\omega) = 2P_1 + 2P_2$ be the preimage of $Z(\eta)$. Since

$$H^0(X, \mathcal{O}_X(P_1 + P_2)) \cong H^0(Y, \mathcal{O}_Y(P) \otimes \mathcal{M}) + H^0(Y, \mathcal{O}_Y(P)),$$

this parity is given by the usual parity of the spin structure on X . Consequently, precisely one of the components of C lies in $\Omega M_3(2, 2)^{\text{odd}}$ and in fact automatically in the hyperelliptic locus \mathcal{L} . We denote this component by C^{odd} .

Theorem 7.1. *The locus \mathcal{D} is strictly contained in \mathcal{L} . More precisely, the intersection $\mathcal{D}^c \cap \mathcal{C}^{\text{odd}}$ is non-empty and strictly contained in \mathcal{C}^{odd} . It consists of orbits of Veech surfaces.*

Proof. First we show that the intersection is not empty. Consider a square-tiled covering of 6 squares as Figure 14.

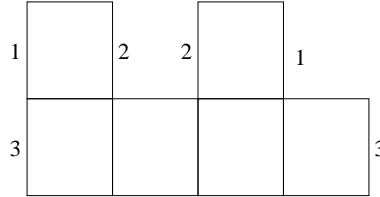


FIGURE 14. A square-tiled surface in \mathcal{L} without $2T_{\text{fix}}2C$ -direction

Horizontal sides are glued by vertical translations. Using e.g. [Sch04], one checks that the affine group of this square-tiled covering has three cusps, given by the horizontal, and vertical direction and by the direction of slope 1. None of these directions is a $2T_{\text{fix}}2C$ -direction.

By [Cal04], a surface in $\mathcal{H}(2)$ which is not Veech has a direction where it splits into a cylinder and a non-periodic torus. Consequently, a covering of a generic surface in $\mathcal{H}(2)$ yields a surface in \mathcal{L} with an irrational $2T_{\text{fix}}2C$ -direction. Such a surface also has a $2T_{\text{fix}}2C$ -direction by Figure 6 (b).

Since the saddle connections involved in a $2T_{\text{fix}}2C$ -direction are homologous, \mathcal{D} is open. Consequently, $\mathcal{D}^c \cap \mathcal{C}^{\text{odd}}$ is closed and $\text{SL}_2(\mathbb{R})$ -invariant. The last claim now follows from [Mc3]. \square

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